

+ 21

# PGAS in C++:

A Portable Abstraction for Distributed  
Data Structures

BENJAMIN BROCK



20  
21



# About Me

- PhD candidate at Berkeley
- Advised by **Kathy Yelick** and **Aydın Buluç**
- Work on **large-scale parallel systems**
- Use a lot of LBL, ORNL **supercomputers**

# This Talk

**Background:** how do we **write a program** for a **supercomputer**?

Introduce **PGAS Model**, RDMA

Building **Remote Pointer** Types

Building **Distributed Data Structures**

Extending to **GPUs**

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# What This Talk Is Not

- A **distributed implementation** of the **STL**
- A full **evaluation** of **parallel computing models**

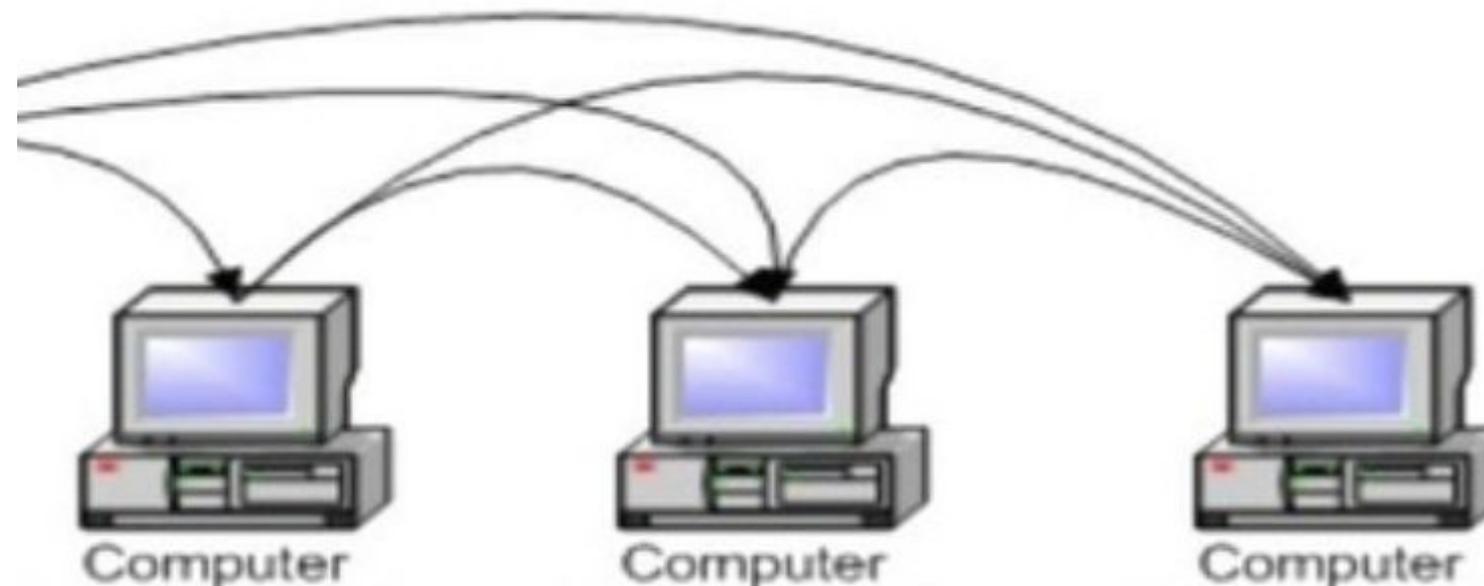
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- A distributed implementation of the **STL**
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# Background: How to supercompute?

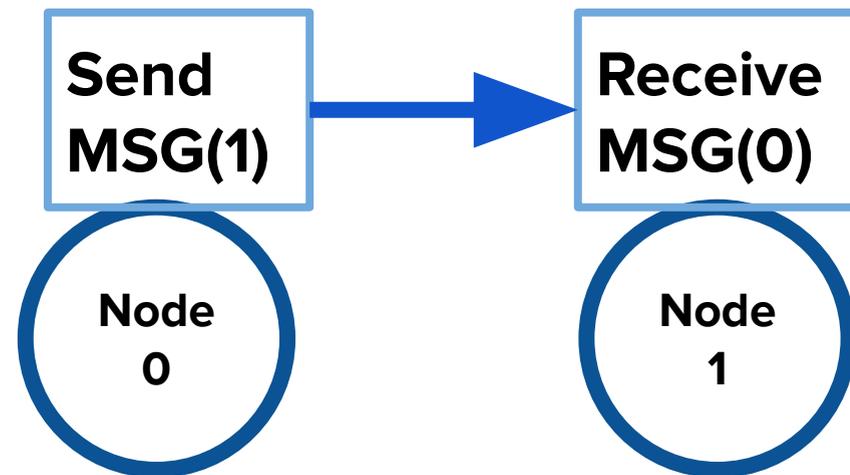
# What is a Cluster?

- A collection of **nodes**, connected by a **network**.



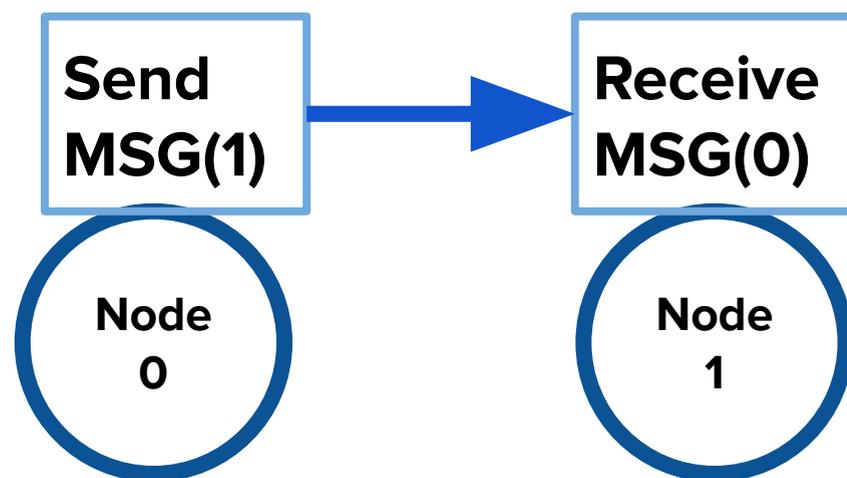
# How do I program one?

- **Message Passing** - processes issue matching **send** and **receive** calls



# How do I program one?

- **Message Passing** - processes issue matching **send** and **receive**



## Process 0

```
// Calculate data
auto values =
    algorithm(1.0f, 3, data);

// Send data to proc. 1
MPI_Send(values.data(),
         values.size(),
         MPI_FLOAT, 1,
         0, MPI_COMM_WORLD);

// Data is now sent.
```

## Process 1

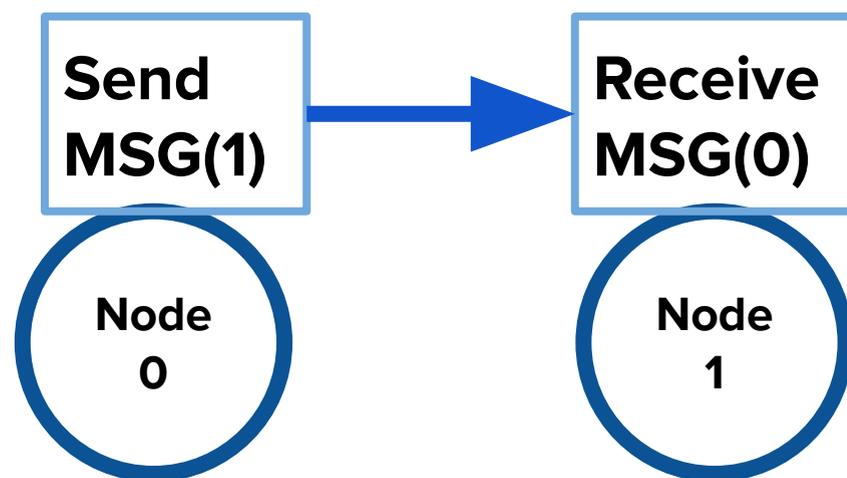
```
// Allocate space for data
std::vector<float>
recv_values(num_values);

// Receive data from proc. 0
MPI_Recv(recv_values.data(),
         num_values,
         MPI_FLOAT, 0,
         0, MPI_COMM_WORLD);

// Data is now in
// `recv_values`
```

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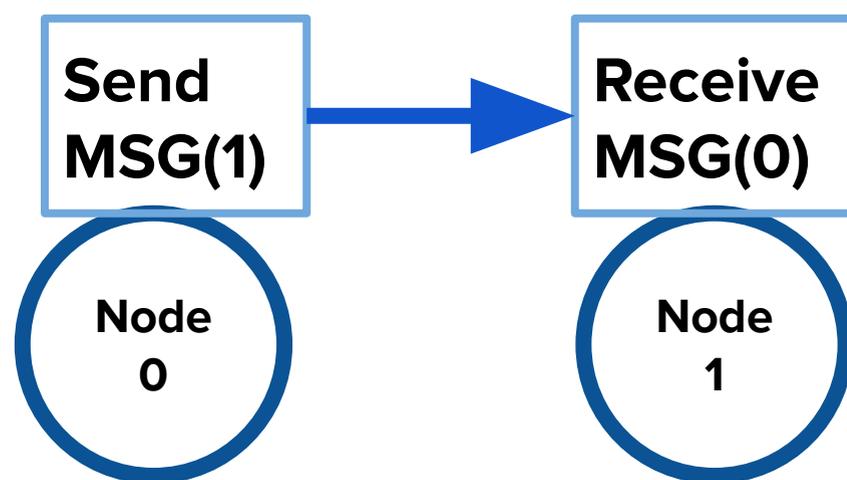
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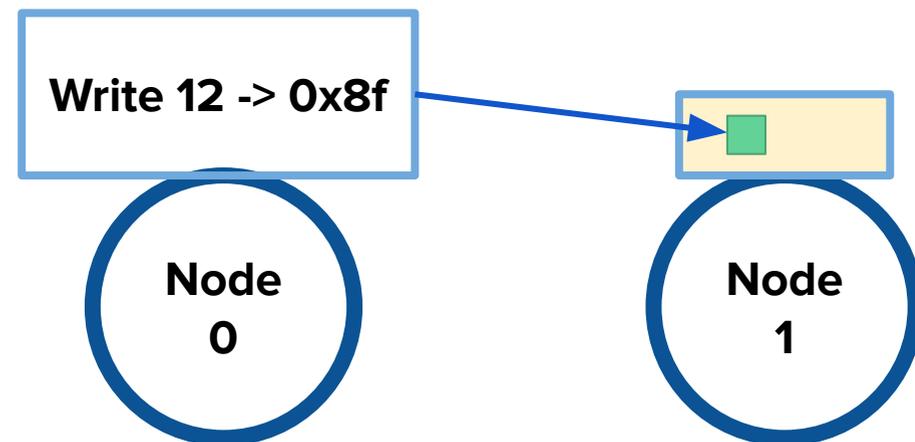


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**P0 and P1 must both participate in message.**

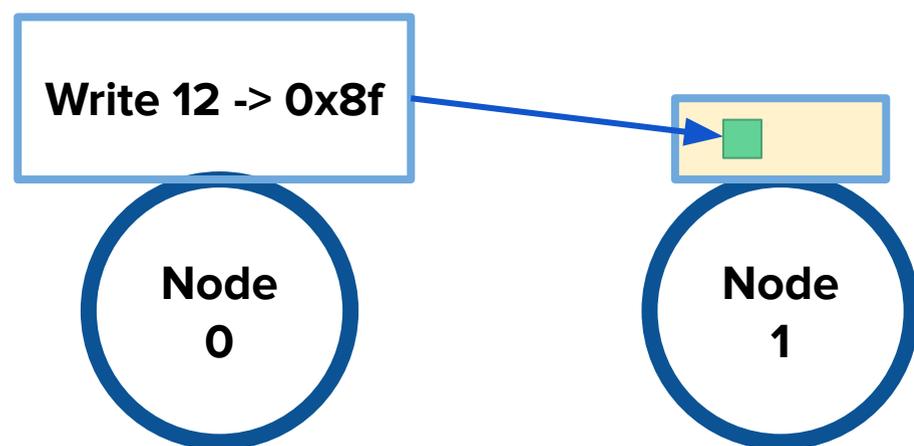
# How do I program one?

- **Message Passing** - processes issue matching **send** and **receive** calls
- **RDMA** - directly read/write to **remote memory**



# How do I program one?

- Message Passing - processes issue matching `send` and `receive` calls
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## Process 0

```
auto remote_ptr = ...;
// Calculate data
auto values = algorithm(1.0f, 3, data);

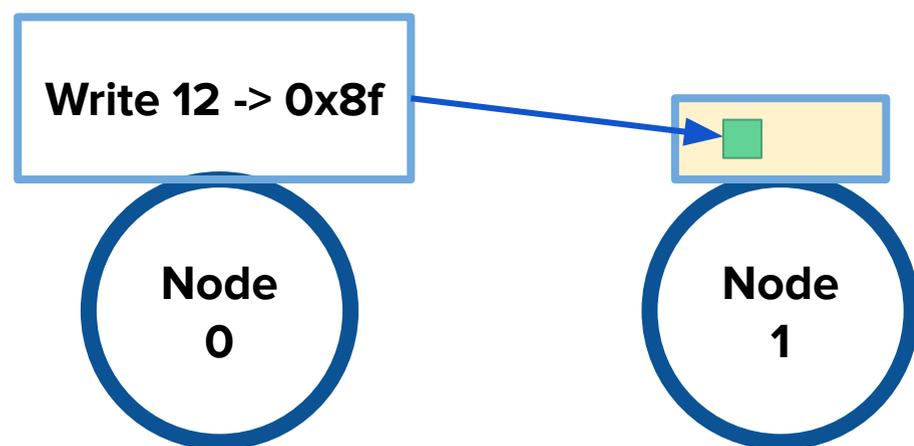
// Send data to proc. 1
BCL::memcpy(remote_ptr, values.data(),
            values.size()*sizeof(float));

BCL::flush();

// Data is copied.
```

# How do I program one?

- Message Passing - processes issue matching `send` and `receive` calls
- **RDMA** - directly read/write to



Process 0

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auto remote_ptr = ...;
// Calculate data
... , data);
... values.data(),
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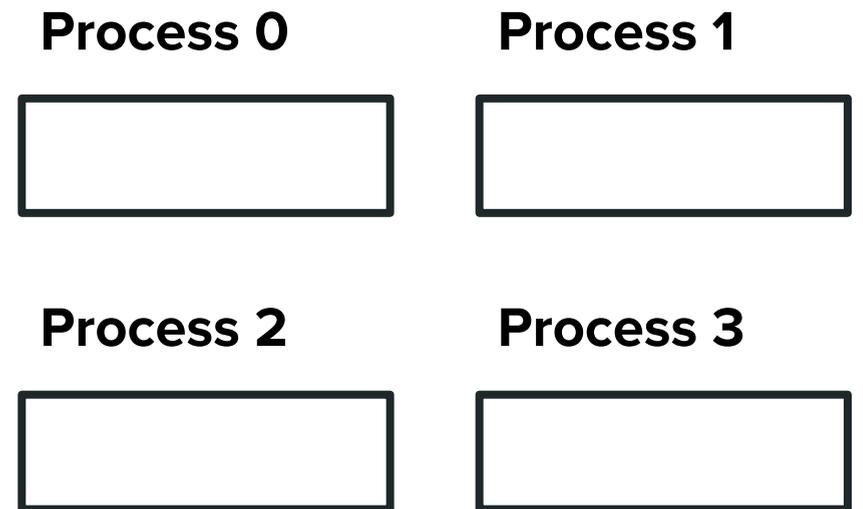
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// Data is copied.
```

**P1 does not participate in remote write.**

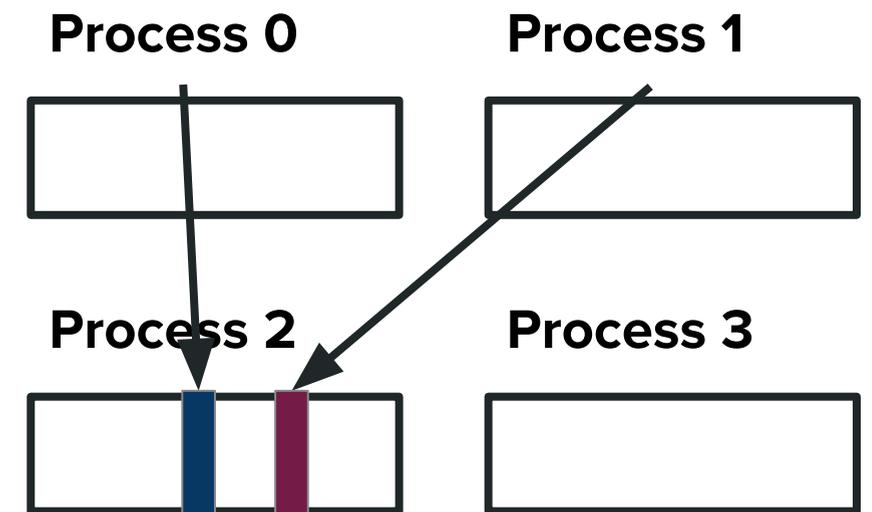
# PGAS Model

- **Partitioned** - each process has its own shared segment
- **Global address space** - each proc's shared segment can be **referenced** by other processes



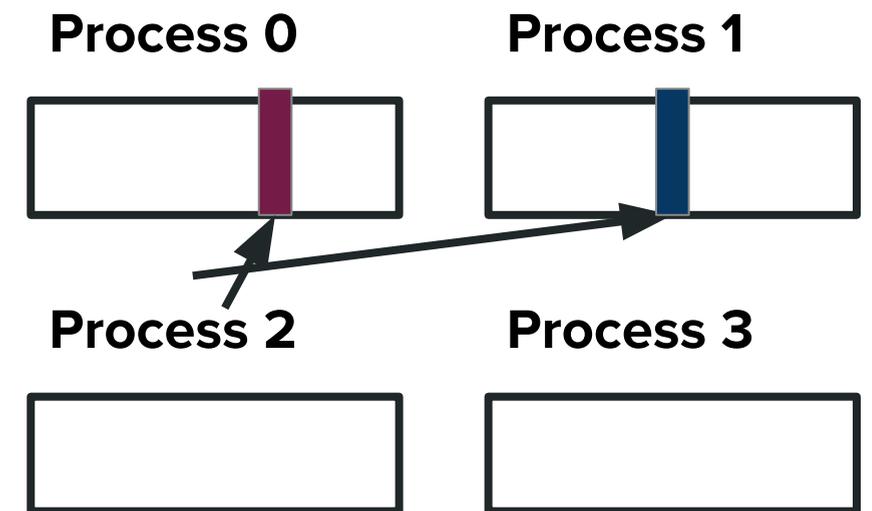
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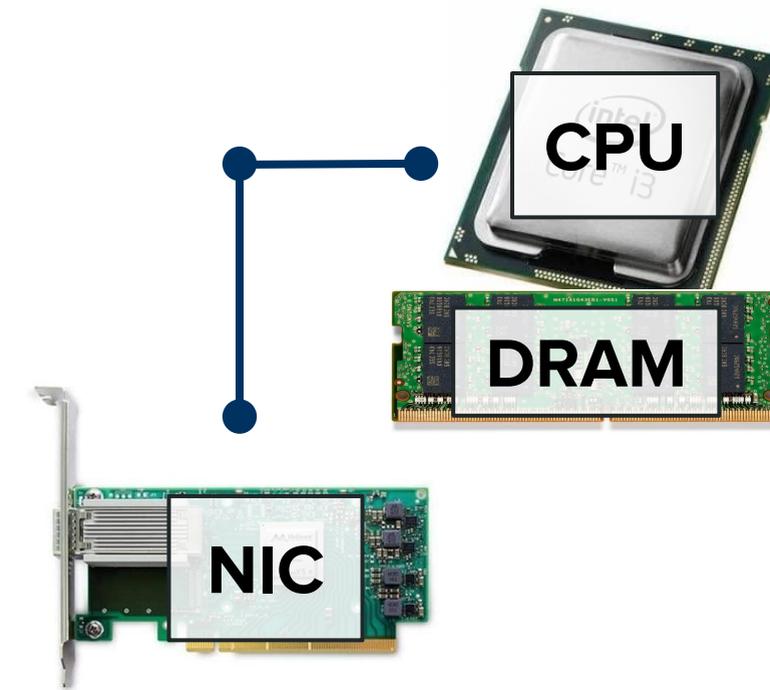
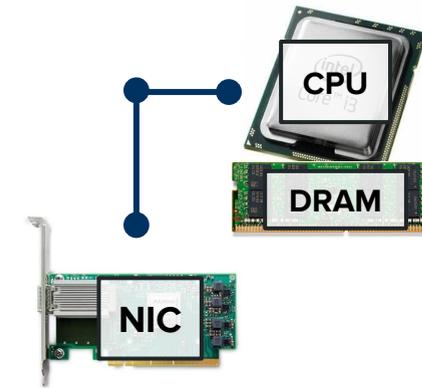
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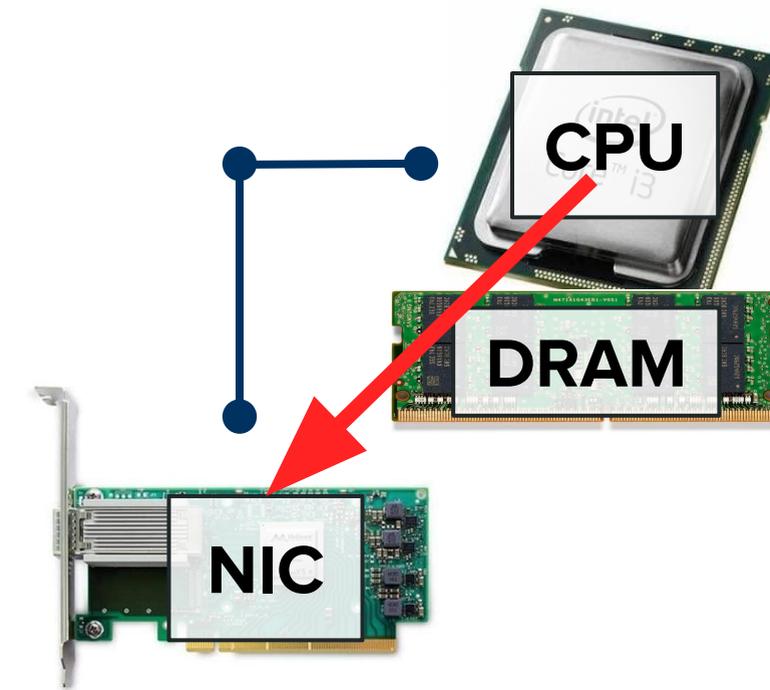
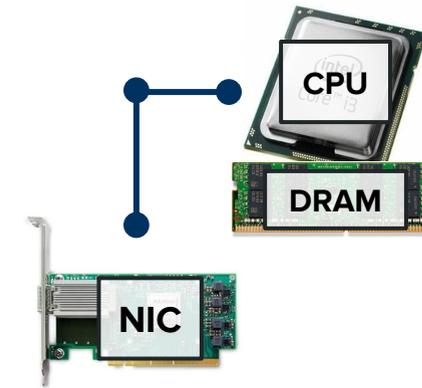
# Advantages of PGAS

- **Asynchronous** - RDMA operations executed by **NIC**
- Allows **irregular**, one-sided access
- Maps well to **data structure** ops



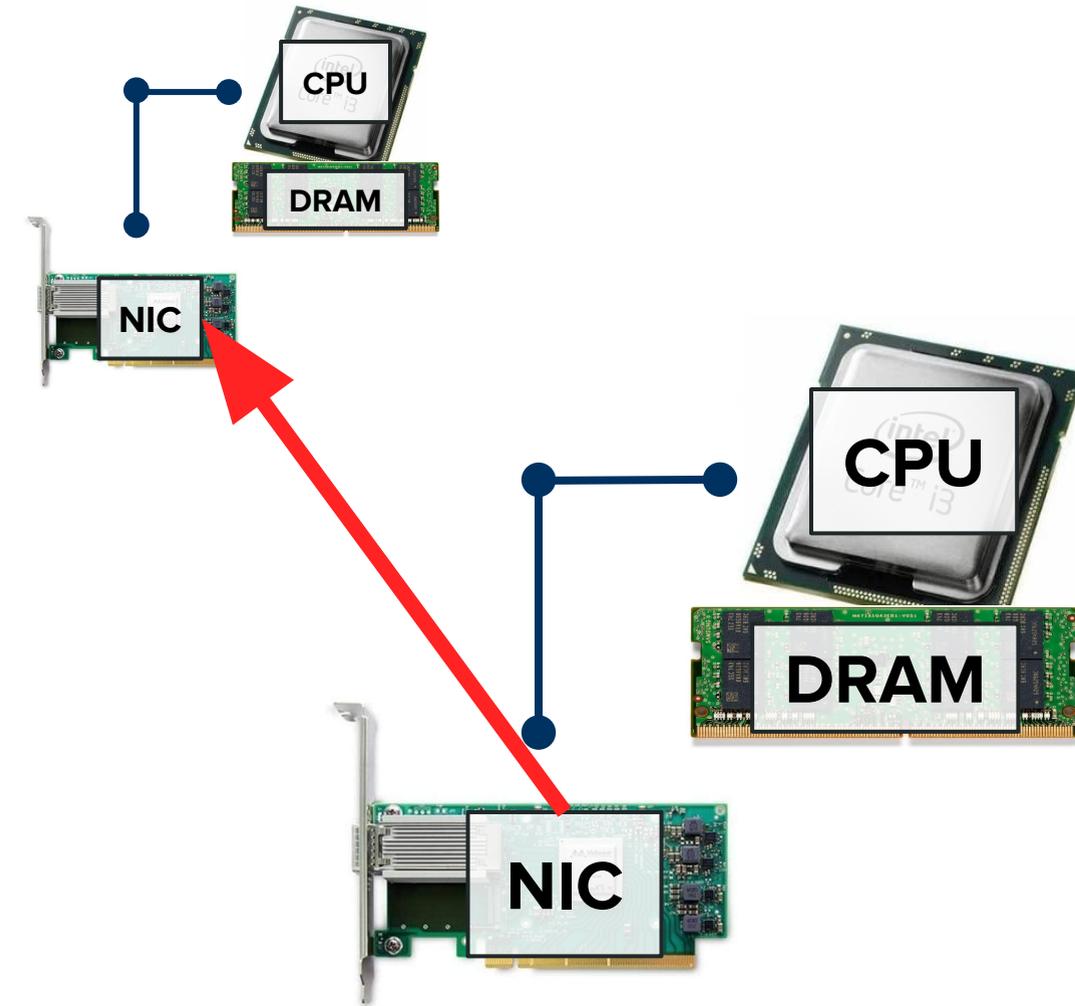
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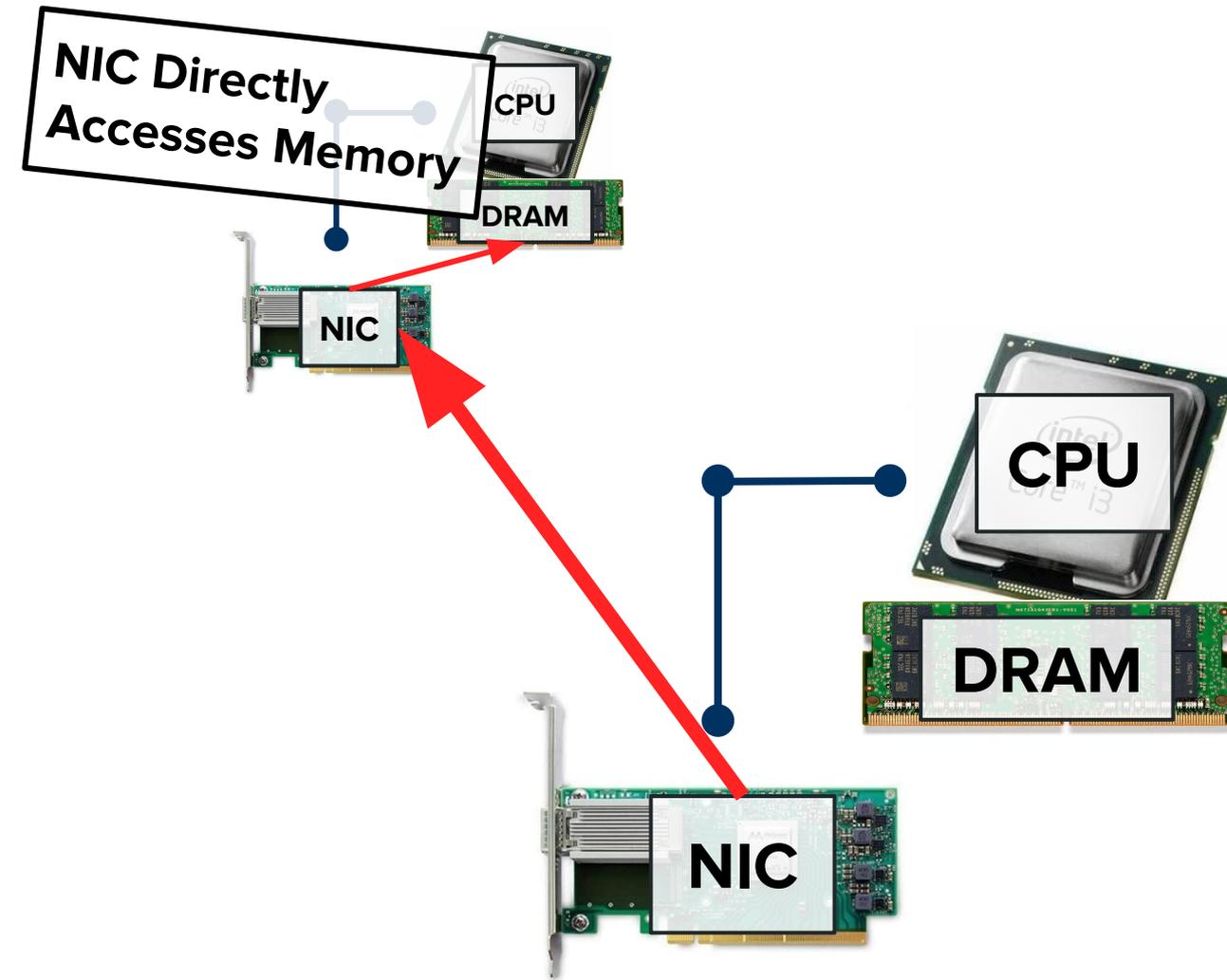
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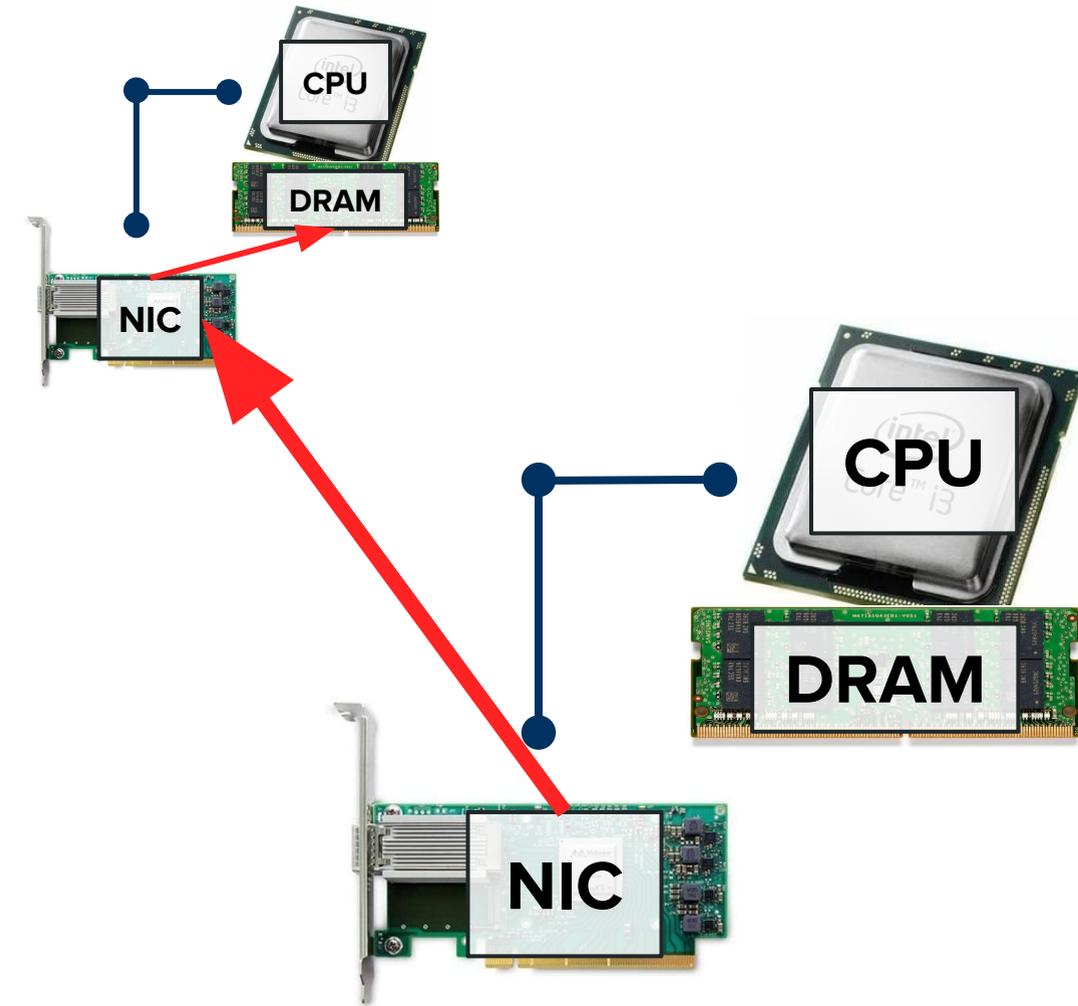
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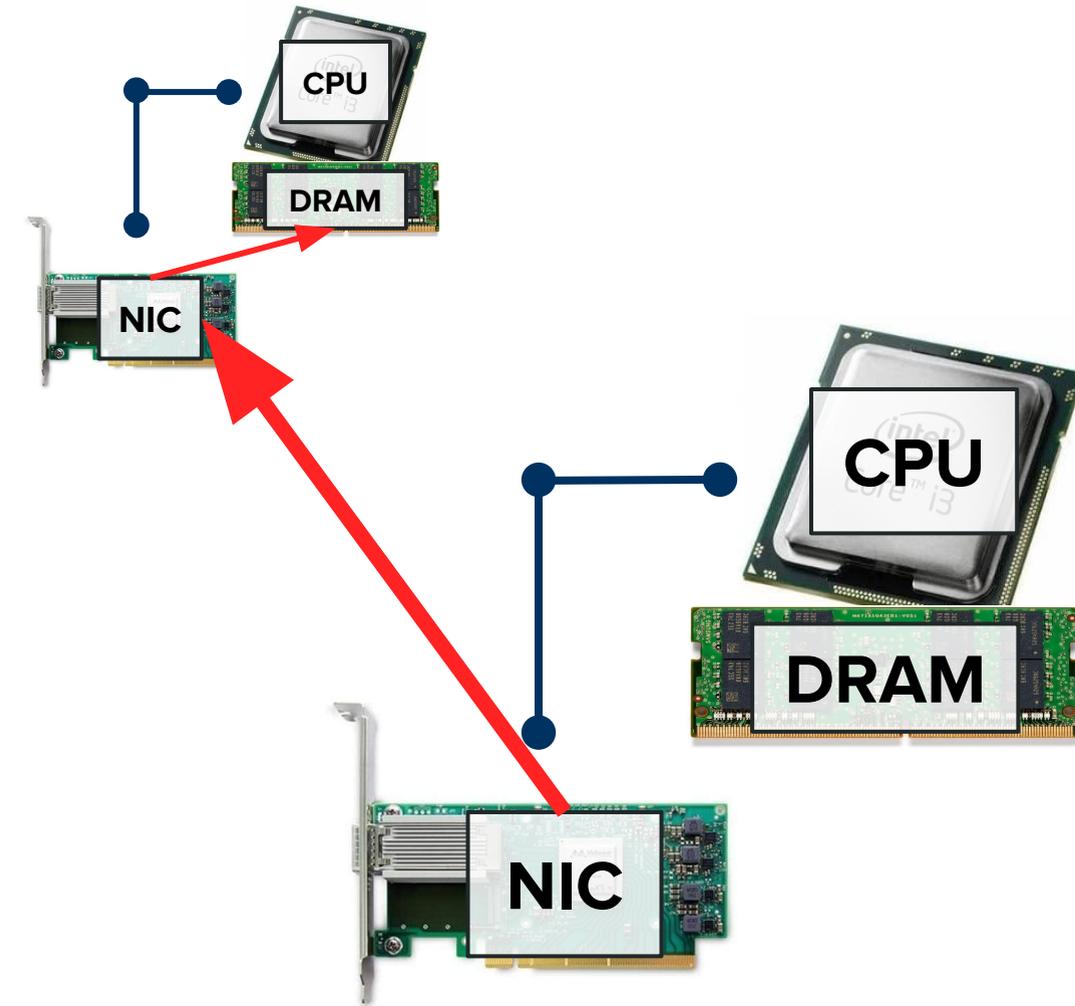
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# Background: Parallel Programs

# Parallel Programs

- **Multiple processes** are executing a program
- Each process has its own **memory space**
- Two methods of communication: **shared memory** and **message passing**

# A SPMD Program

```
#include <bcl/bcl.hpp>
#include <fmt/core.h>

int main(int argc, char** argv) {
    BCL::init();

    fmt::print("Hello from rank {}\n",
              BCL::rank());

    BCL::finalize();
    return 0;
}
```

# A SPMD Program

Output: `mpirun -n 4 ./test`

```
#include <bcl/bcl.hpp>
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int main(int argc, char**
    BCL::init();

    fmt::print("Hello from
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```
$ mpirun -n 4 ./test
Hello from rank 0
Hello from rank 1
Hello from rank 2
Hello from rank 3
```

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$ mpirun -n 4 ./test
Hello from rank 0
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Hello from rank 3
```

**Each process runs  
the same program.**



# A SPMD Program

```
#include <bcl/bcl.hpp>
#include <fmt/core.h>

int main(int argc, char** argv) {
    BCL::init();

    if (BCL::rank() == 2) {
        fmt::print("Rank 2 says hi!\n");
    }

    BCL::finalize();
    return 0;
}
```

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Rank 2 says hi!
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    BCL::finalize();
    return 0;
}
```

```
$ mpirun -n 4 ./test
Rank 2 says hi!
```

**Only one process  
runs portion in if  
statement.**

# Remote Pointers

# Remote Pointers

- Remote pointers are **smart pointer classes** that **may reference remote memory**
- 1)** We can use a remote pointer to do an **RDMA get / put**
- 2)** Can also perform **atomic operations** (e.g. fetch-and-add, compare-and-swap)
- 3)** If pointing to **shared memory in the current process**, can convert to regular (local) pointer

# Building a Remote Pointer Type

```
template <typename T>
struct GlobalPtr {

    ...

private:
    size_t rank_;
    size_t offset_;
};
```

# Remote Pointer Types

```
template <typename T>
struct GlobalPtr {
    ...

private:
    size_t rank_;
    size_t offset_;
};
```

```
void memcpy(void* dest,
            GlobalPtr<void> src,
            size_t n) {
    // Issue remote get operation to
    // copy `n` bytes from `src` to `dest`
    backend::remote_get(dest, src, n, ...);
}
```

# Remote Pointer Types

- Can build **memcpy** to support **reading/writing** from/to remote memory
- Can write `fetch_and_op`, `compare_and_swap`, etc. **atomic ops**
- Can **dereference** remote pointer

# Remote Pointer Types

```
template <typename T>
struct GlobalPtr {

    ...

    GlobalRef<T> operator*() {
        return GlobalRef<T>>(*this);
    }

private:
    size_t rank_;
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# Remote Pointer Types

```
template <typename T>
struct GlobalPtr {
    ...

    GlobalRef<T> operator*() {
        return GlobalRef<T>(*this);
    }

private:
    size_t rank_;
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};
```

**Not possible to return a regular T&, since memory may be remote.**

# Remote Pointer Types

```
template <typename T>
struct GlobalPtr {
    ...

    GlobalRef<T> operator
        return GlobalRef<T>
    }

private:
    size_t rank_;
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};
```

```
template <typename T>
struct GlobalRef {
    T& operator=(const T& value) {
        memcpy(ptr_, &value, sizeof(T));
        return value;
    }

    operator T() const {
        T value;
        memcpy(&value, ptr_, sizeof(T));
        return *static_cast<T*>(value);
    }

private:
    GlobalPtr<T> ptr_;
};
```

# Remote Pointer Types

- Allow referencing memory on **another process**
- Can support **memcpy**, **atomics**, pointer arithmetic, etc.
- Can support **dereferencing**, but must have **custom reference type** (cannot use **T&** across nodes)
- Limited to **trivially copyable** types

# BCL Global Pointer Example

```
BCL::GlobalPtr<int> ptr = nullptr;

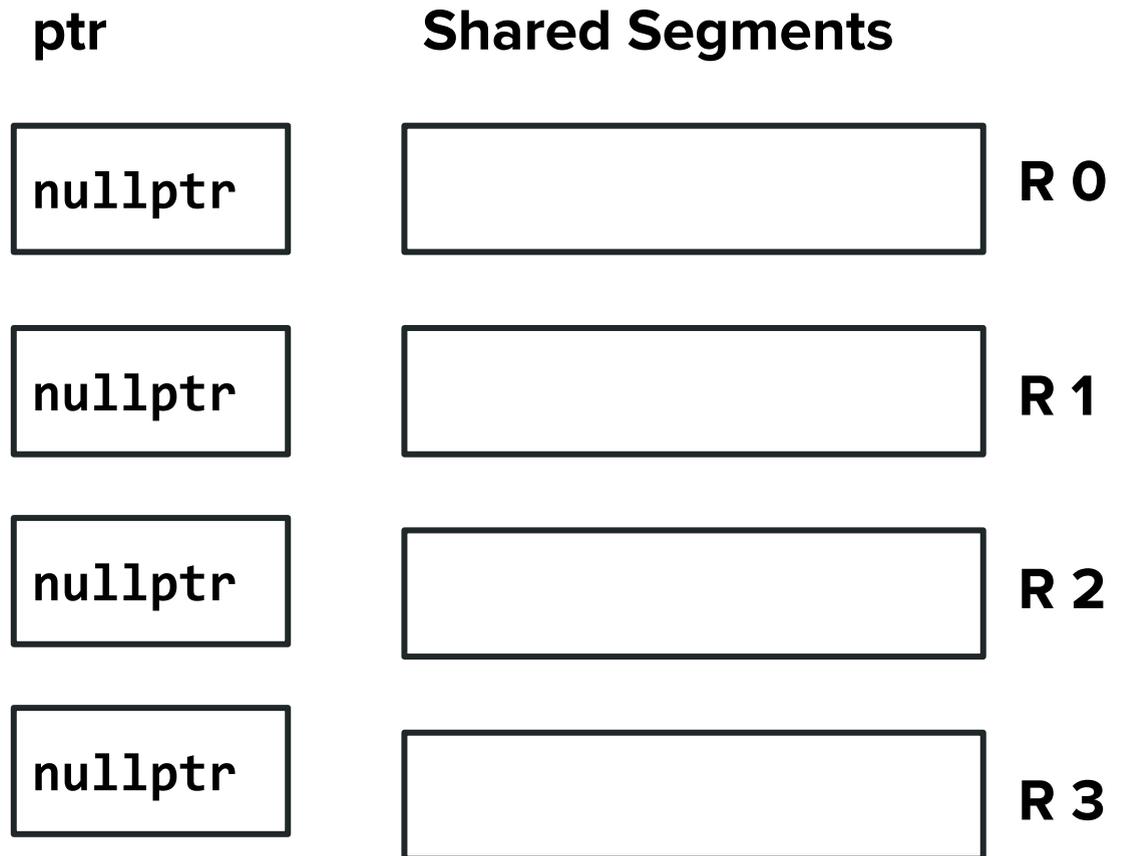
if (BCL::rank() == 0) {
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}

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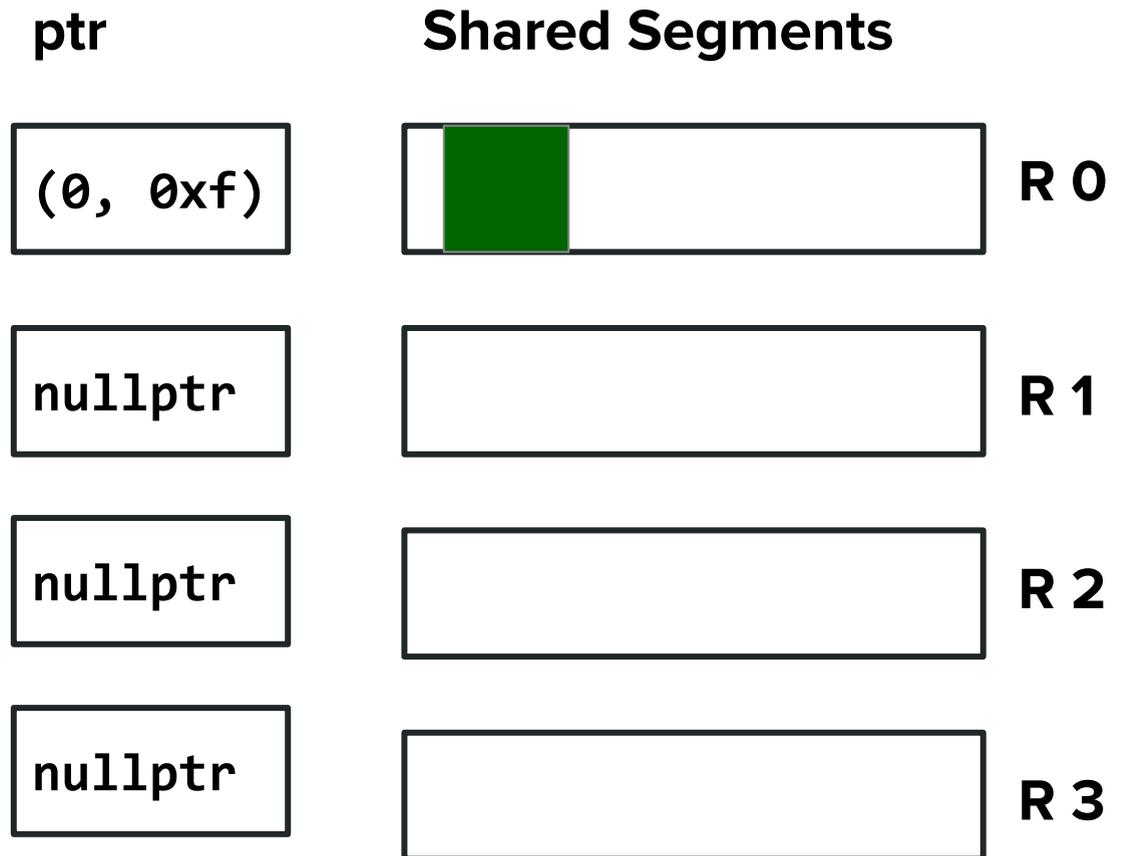
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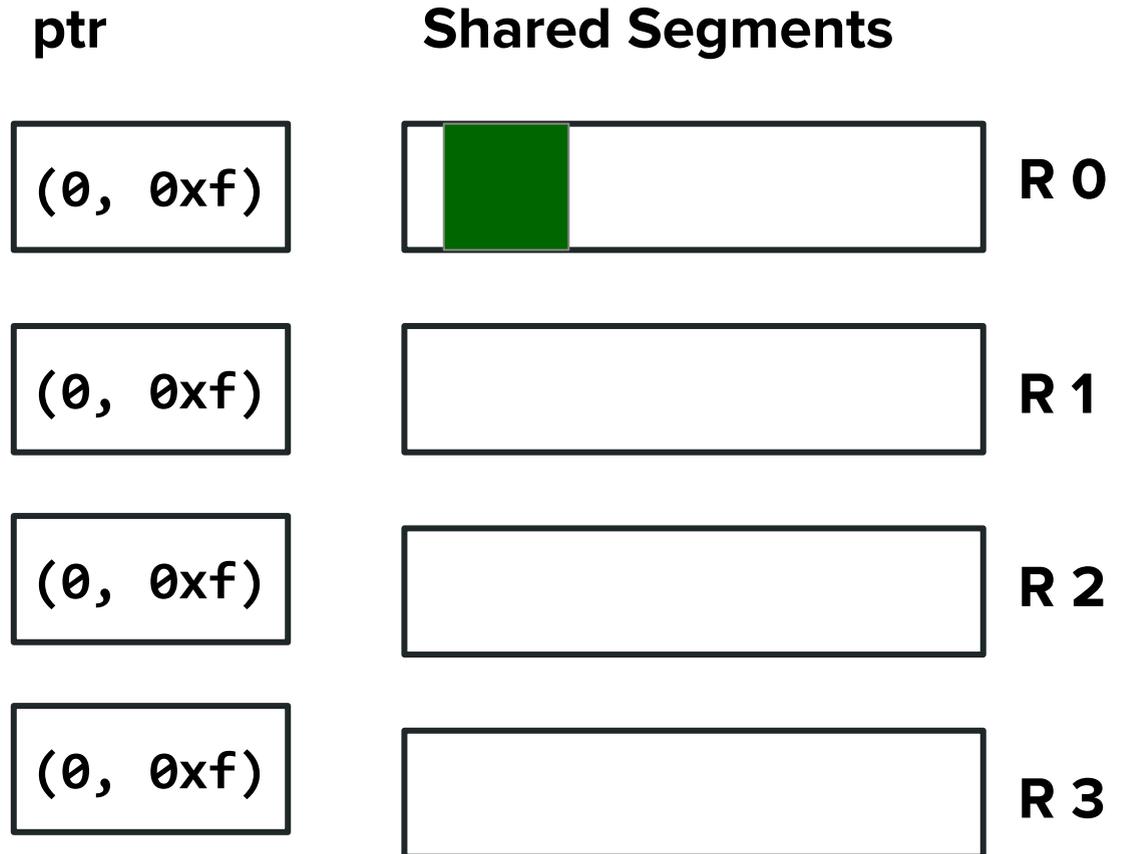
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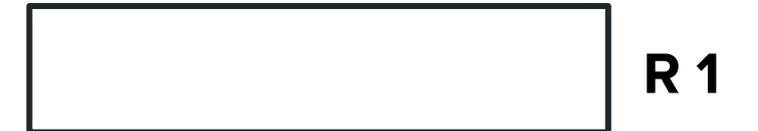
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Shared Segments



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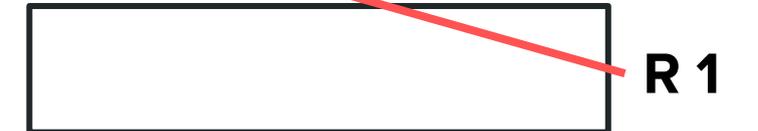
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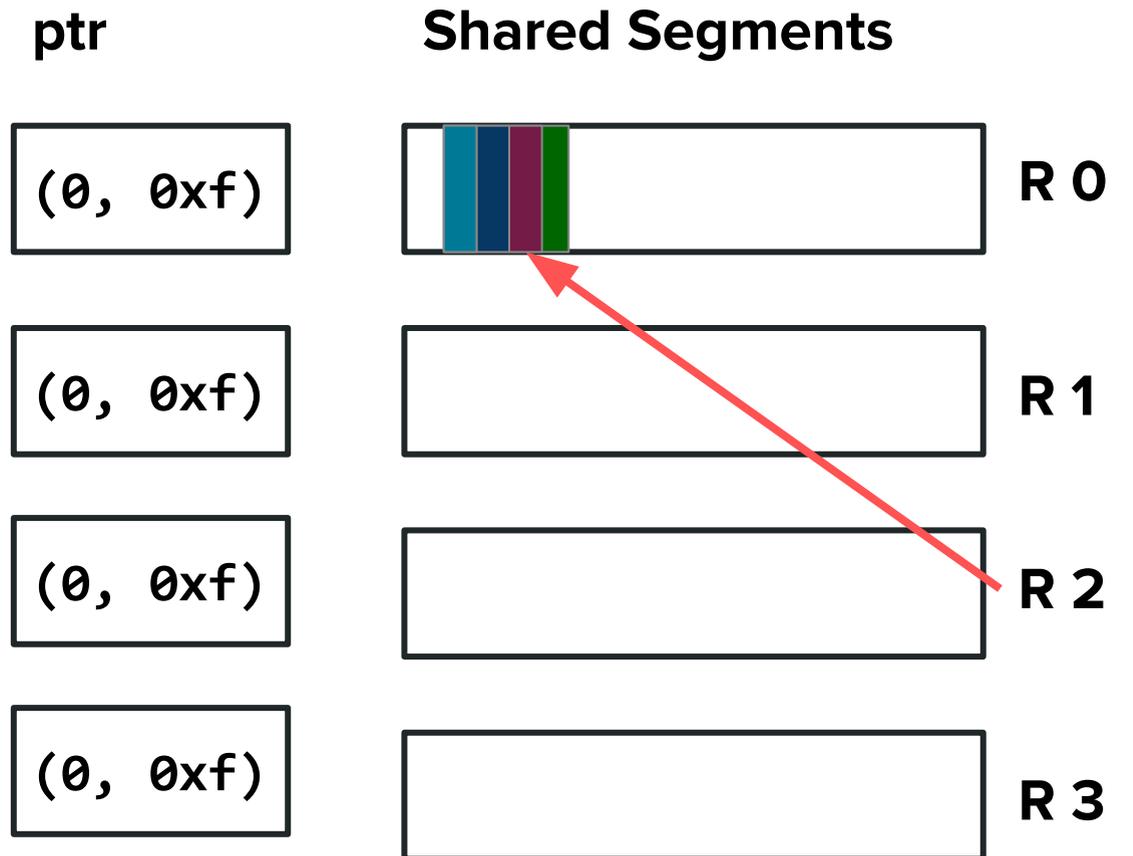
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Shared Segments

R 0

R 1

R 2

R 3

# Data Structures

# Data Structures

- Data structures are **split into two types**:

- 1) **Remote** data structures

- Data **located** on a **single process**
- **Globally** accessible

- 2) **Distributed** Data structures

- Data **distributed** across many processes
- **Globally** accessible

# Data Structures

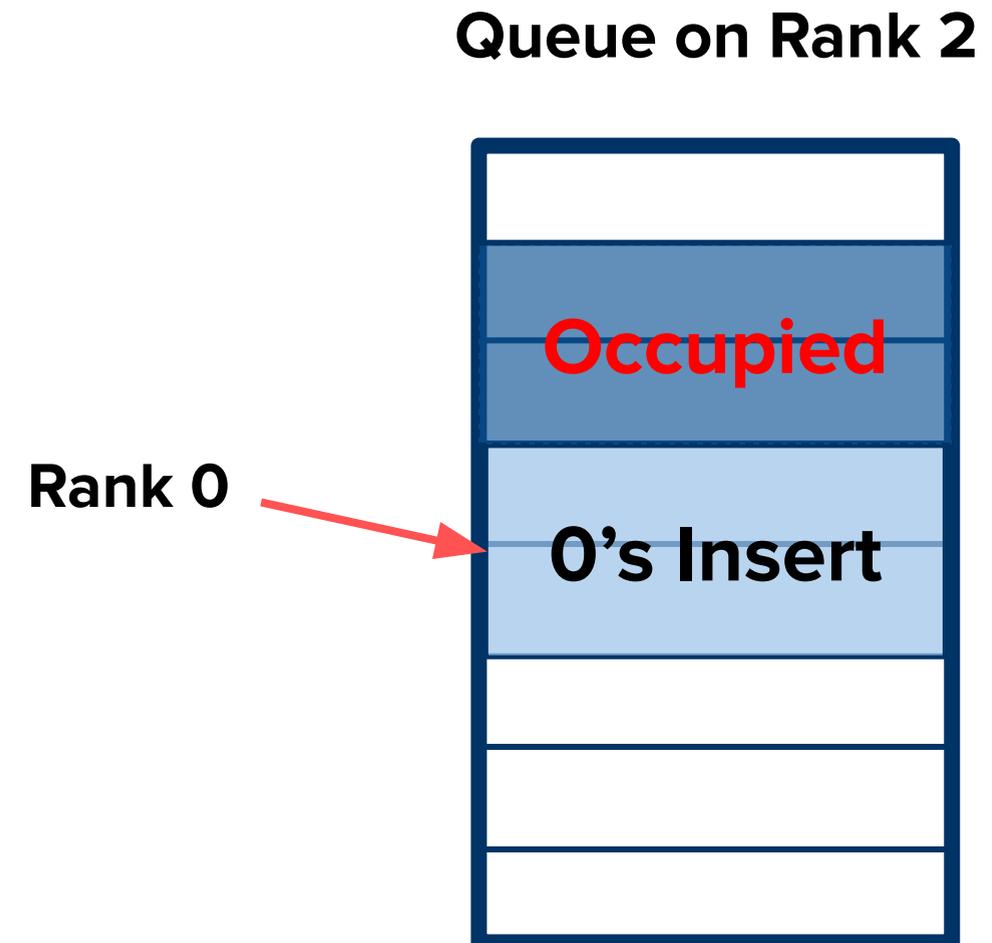
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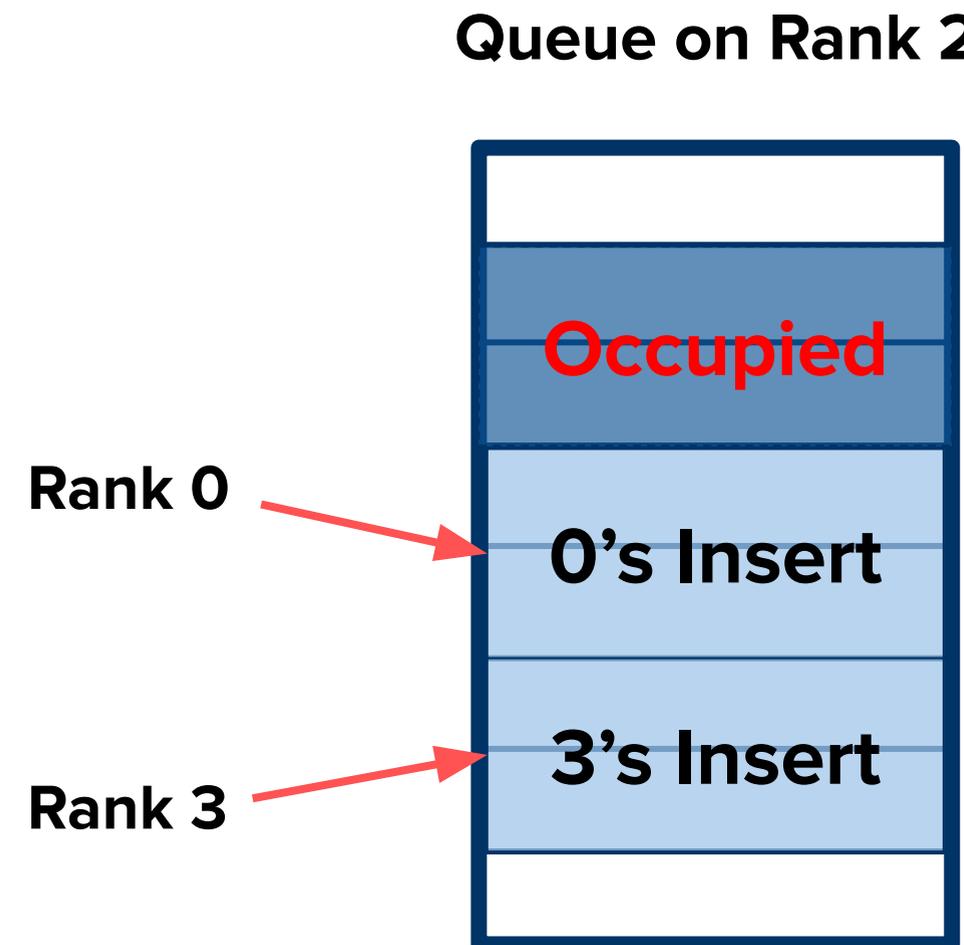
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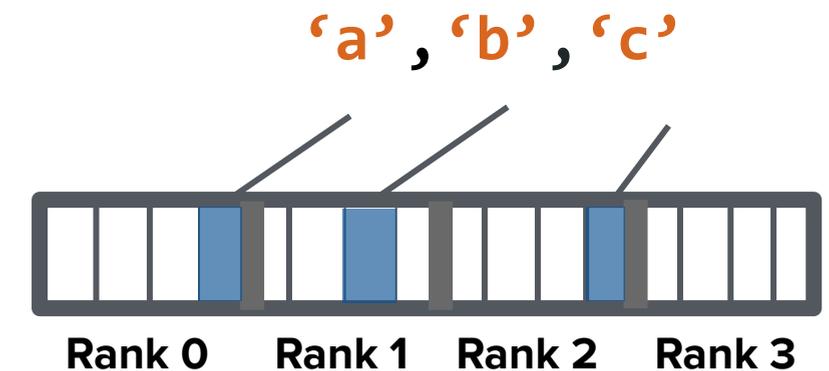
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### Distributed Hash Table



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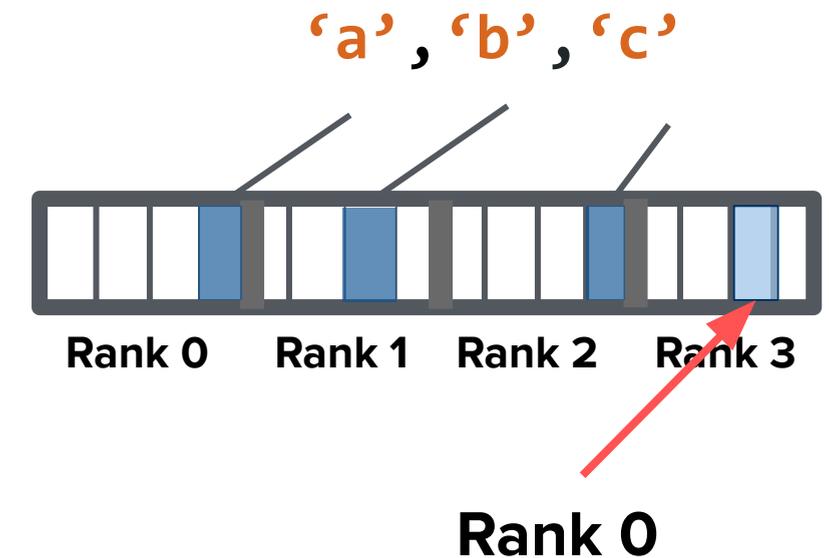
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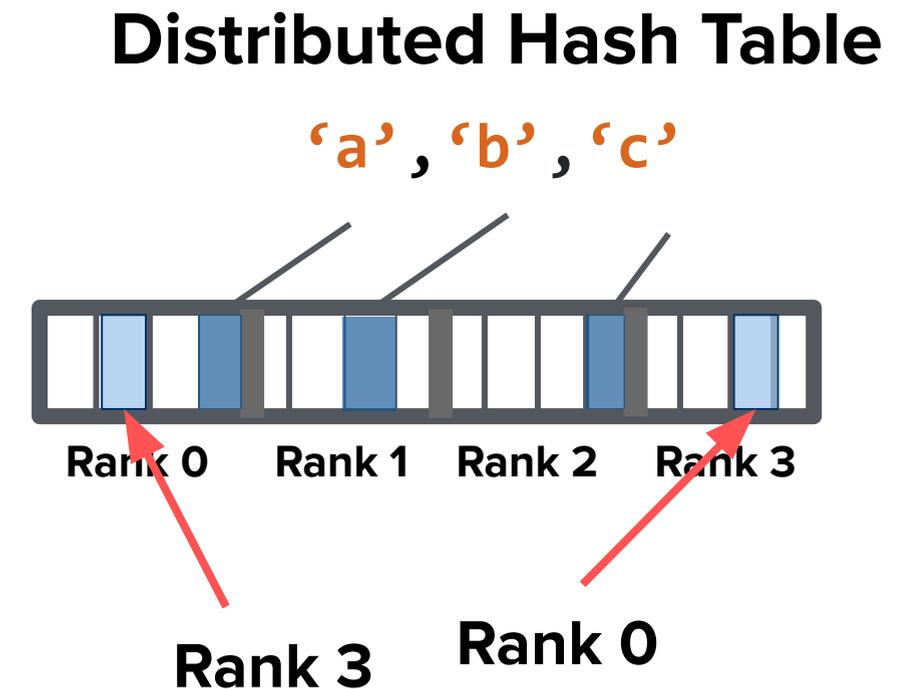
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# Data Structures

- **Constructors/destructors** that must be called **collectively**
- Each process has **global view** of data structure
- **Most methods** (e.g. insert, find) not collective

```
#include <bcl/bcl.hpp>

int main(int argc, char **argv) {
    BCL::init();

    BCL::HashMap<std::string, int> map(BCL::nprocs());

    if (BCL::rank() == 0) {
        for (int i = 0; i < BCL::nprocs(); i++) {
            map.insert({std::to_string(i), i});
        }
    }
    ...
}
```

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        }
    }
    ...
}
```

**Each process invokes constructor collectively**



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    BCL::HashMap<std::string, int> map(BCL::nprocs());

    if (BCL::rank() == 0) {
        for (int i = 0; i < BCL::nprocs(); i++) {
            map.insert({std::to_string(i), i});
        }
    }
    ...
}
```

# Data Structures

- **Constructors/destructors** that must be called **collectively**
- Each process has **global view** of data structure
- **Most methods** (e.g. insert, find) not collective

```
#include <bcl/bcl.hpp>

int main(int argc, char **argv) {
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    BCL::HashMap map(BCL::nprocs());

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        }
    }
    ...
}
```

**Rank 0 inserts**

# Iteration - Global and Local

- “**Global Iteration**” supported over **distributed range** of elements
- “**Local iteration**” supported over **local range** of elements

```
#include <bcl/bcl.hpp>

int main(int argc, char **argv) {
    BCL::init();

    BCL::HashMap<std::string, int> map = ...;

    if (BCL::rank() == 0) {
        for (auto iter = map.begin();
             iter != map.end(); ++iter) {
            auto&& [key, value] = *iter;
            fmt::print("{}: {}", key, value);
        }
    }
    ...
}
```

# Iteration - Global and Local

- “**Global Iteration**” supported over **distributed range** of elements
- “**Local iteration**” supported over **local range** of elements in process’ memory

```
#include <bcl/bcl.hpp>

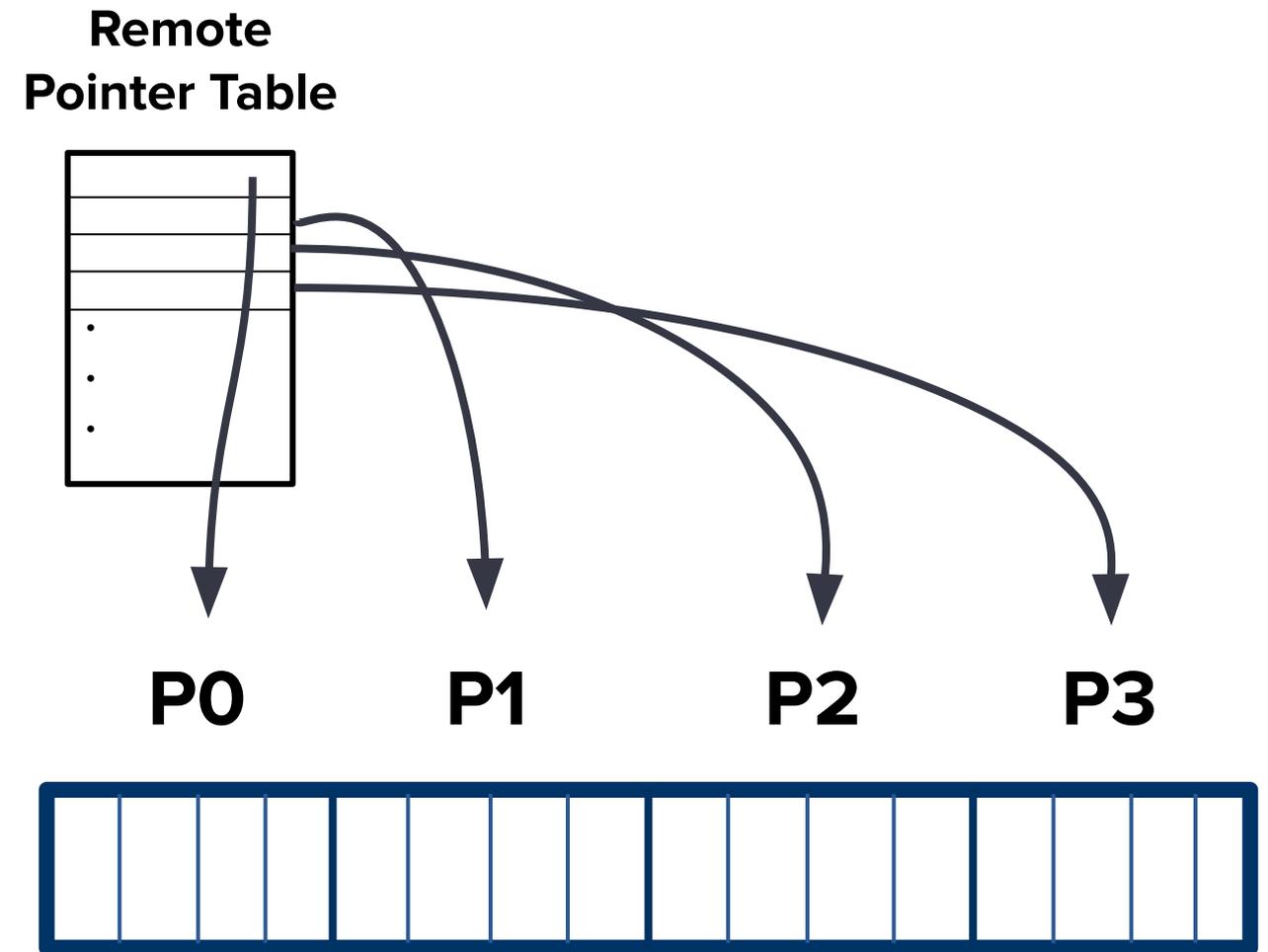
int main(int argc, char **argv) {
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    BCL::HashMap<std::string, int> map = ...;

    if (BCL::rank() == 0) {
        for (auto iter = map.local_begin();
             iter != map.local_end(); ++iter) {
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            fmt::print("{}: {}", key, value);
        }
    }
    ...
}
```

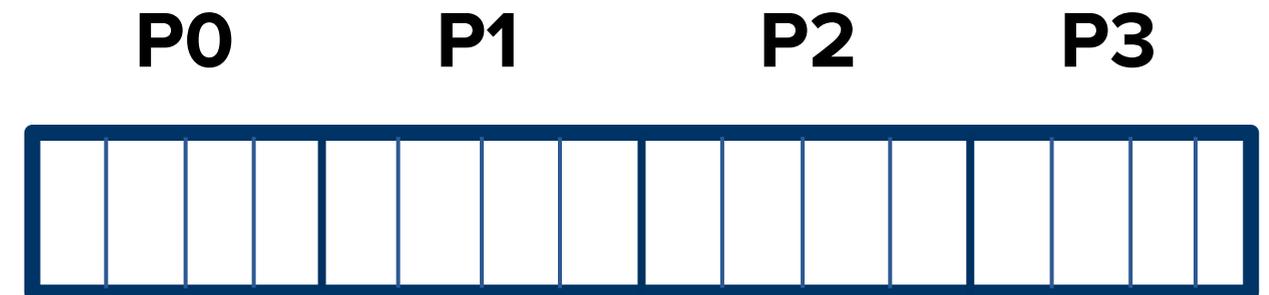
# Distributed Hash Table

- Open addressing -- hash table buckets are split among procs
- To manipulate a bucket, **directly read/write using RDMA.**
- **Resizing** must be done collectively



# Distributed Hash Table

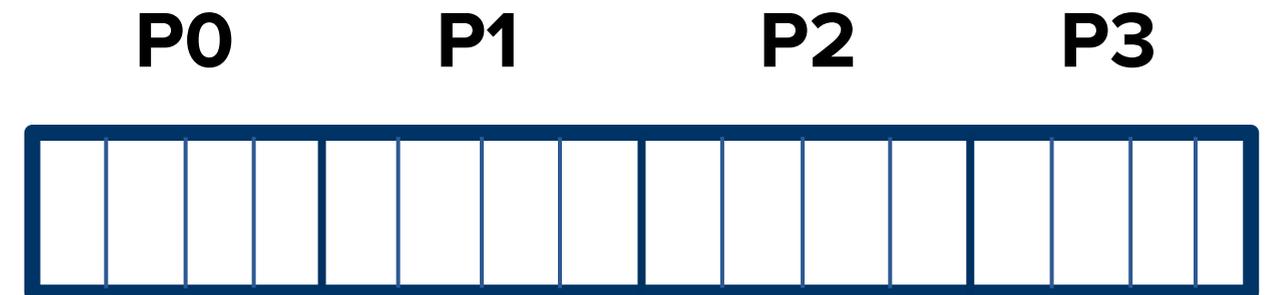
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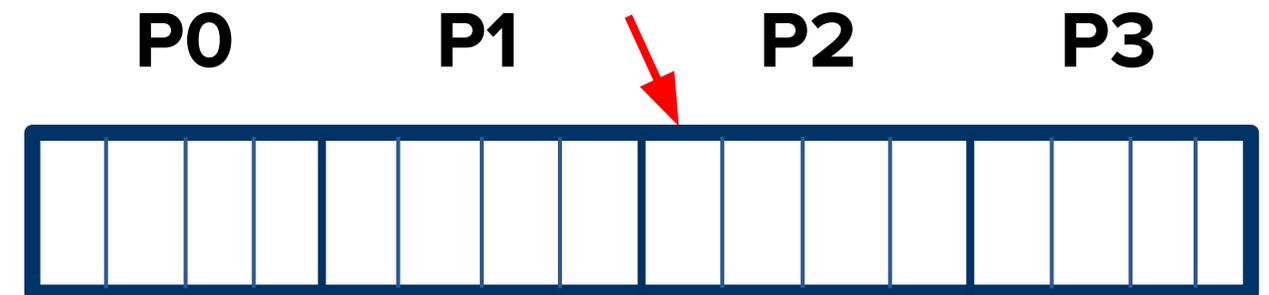
**insert({k, v})**



# Distributed Hash Table

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**insert({k, v})**  
1) Calculate location



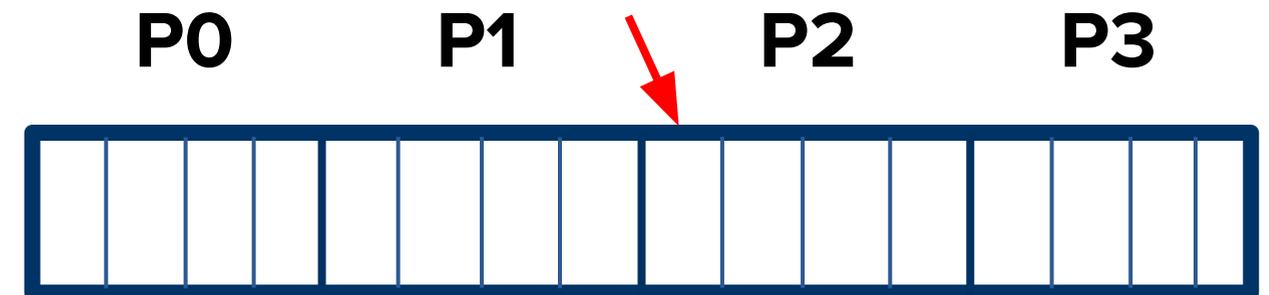
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**insert({k, v})**

**1) Calculate location**

**2) Request bucket ( $A_{FAO}$ )**

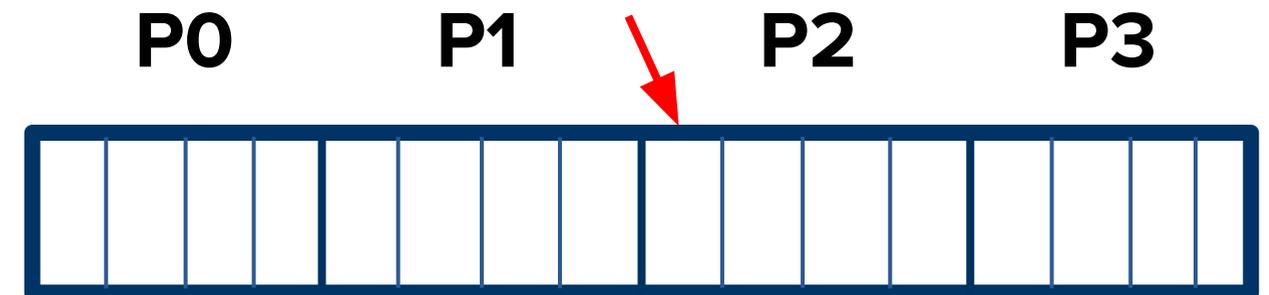


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- 3) Insert item (W)

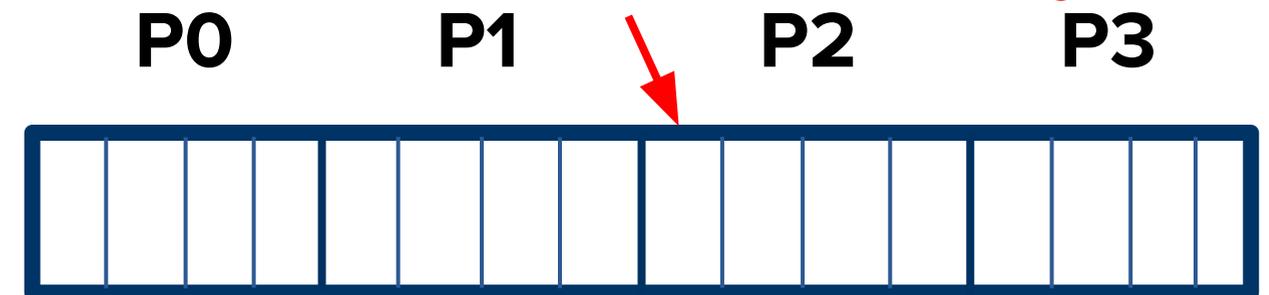


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**insert({k, v})**

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- 4) Mark bucket ready ( $A_O$ )



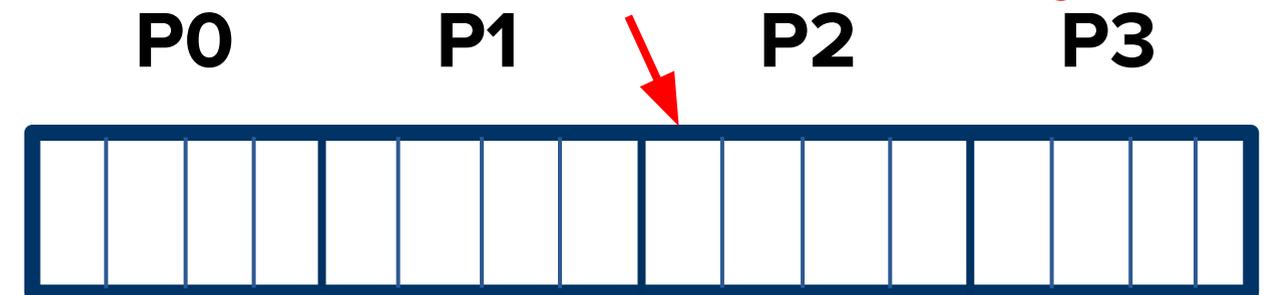
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# Distributed Hash Table

- Open addressing -- hash table buckets are split among procs
- To manipulate a bucket, **directly read/write using RDMA.**
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**Best Case Cost:  $A_{FAO} + W (+ A_o)$**

**Latency bound!  
Can we do better?**

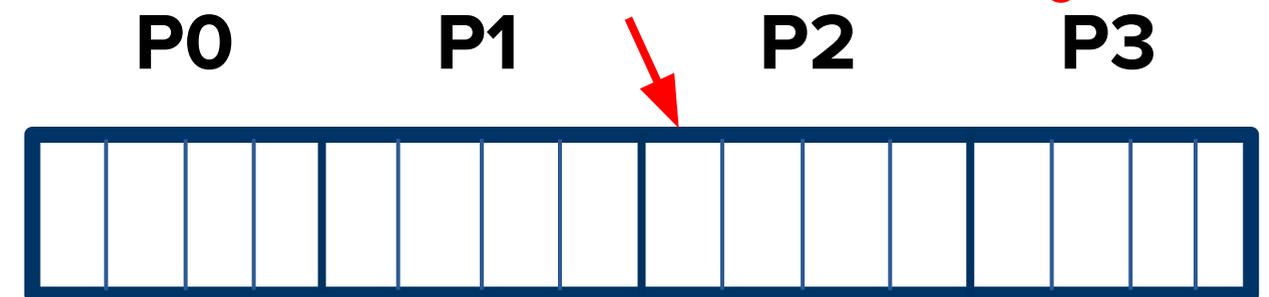
**$(k, v)$**

**late location**

**st bucket ( $A_{FAO}$ )**

**3) Insert item ( $W$ )**

**4) Mark bucket ready ( $A_o$ )**



# HashMapBuffer

- Constructed from a **HashMap**
- Similar to a **range adaptor**, but relaxes when operations take place
- **Aggregates** fine-grained insertions into large transfers

```
#include <bcl/bcl.hpp>

int main(int argc, char **argv) {
    BCL::init();

    BCL::HashMap<std::string, int> map = ...;

    BCL::HashMapBuffer<std::string, int> buf(map);

    for (const auto&& value : data) {
        buf.insert({value.key, value.value});
    }
    buf.flush();
    ...
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```

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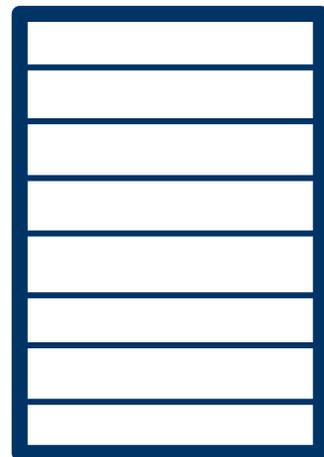
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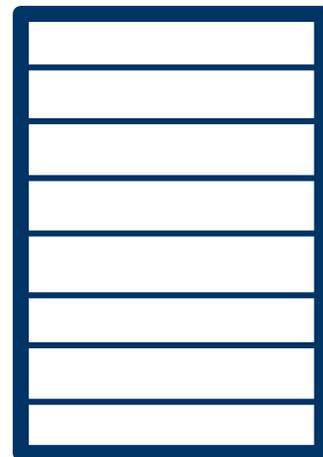
# Bulk Transfers Using Queues

Queues allow **asynchronous all-to-all communication**

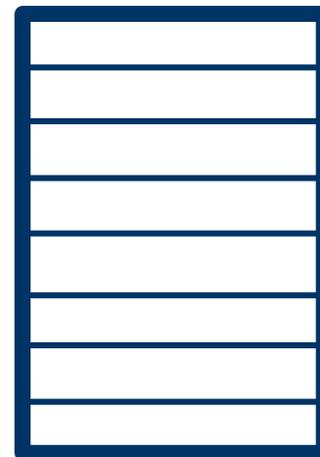
**Rank 0**



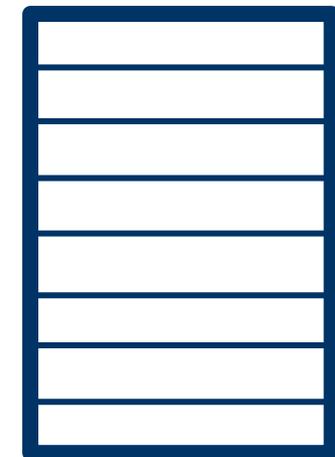
**Rank 1**



**Rank 2**

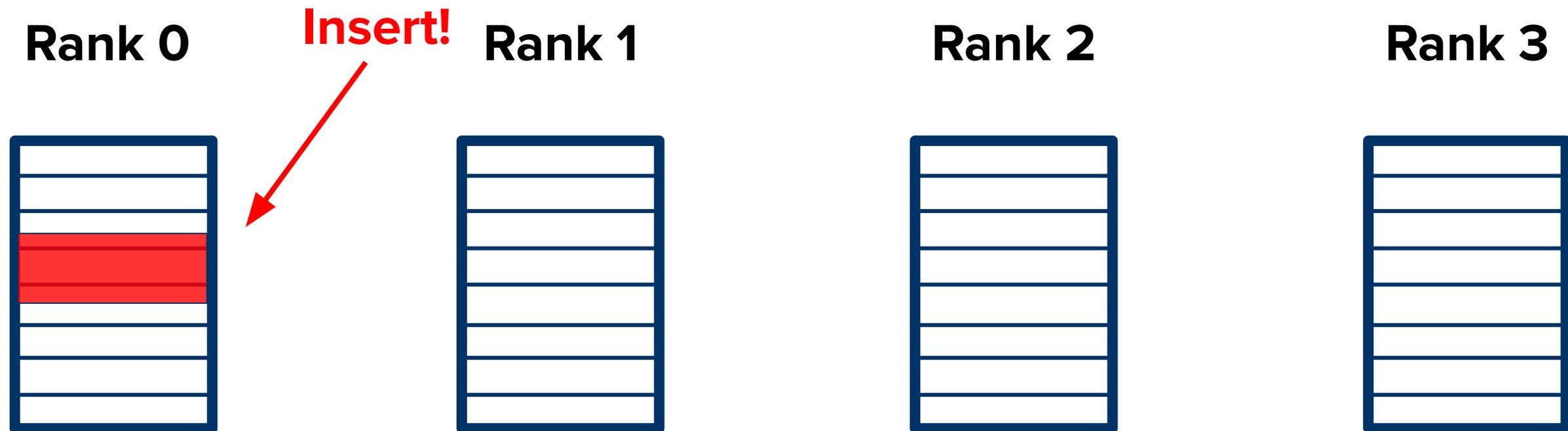


**Rank 3**



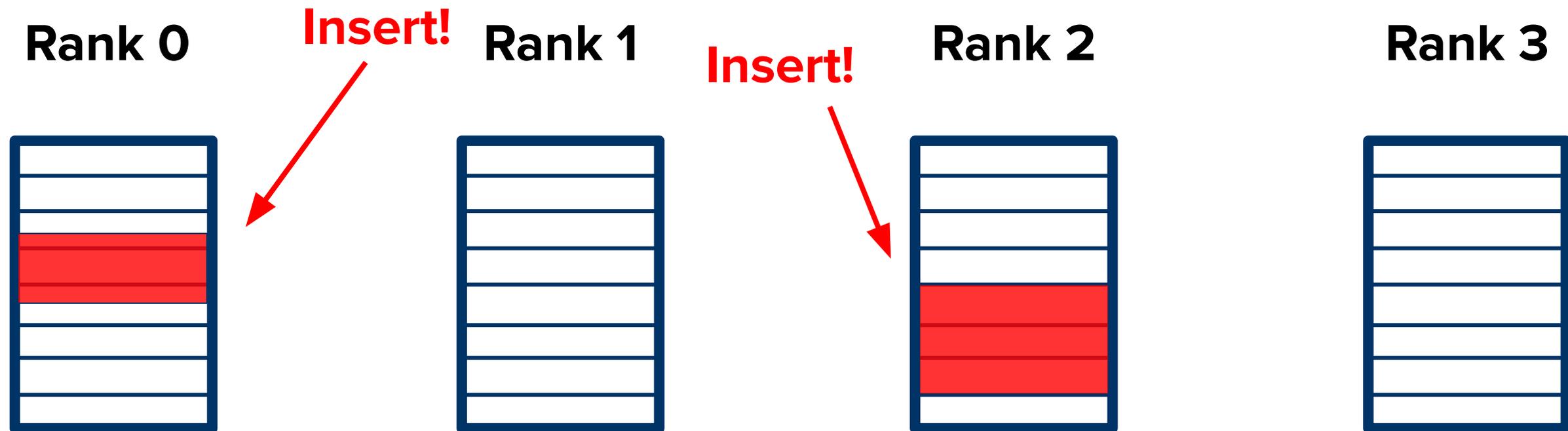
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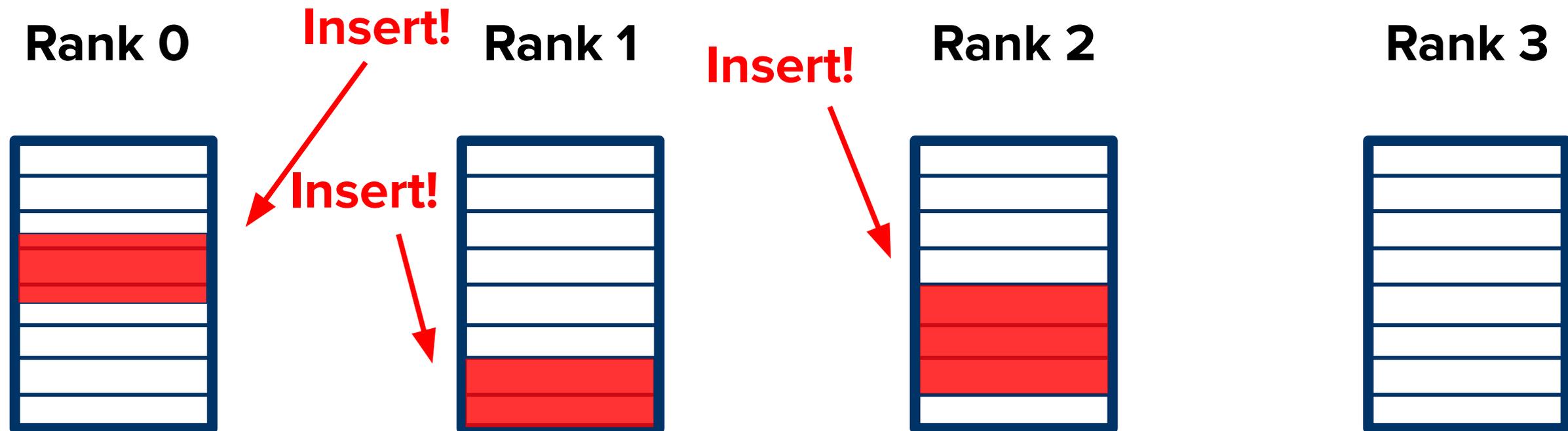
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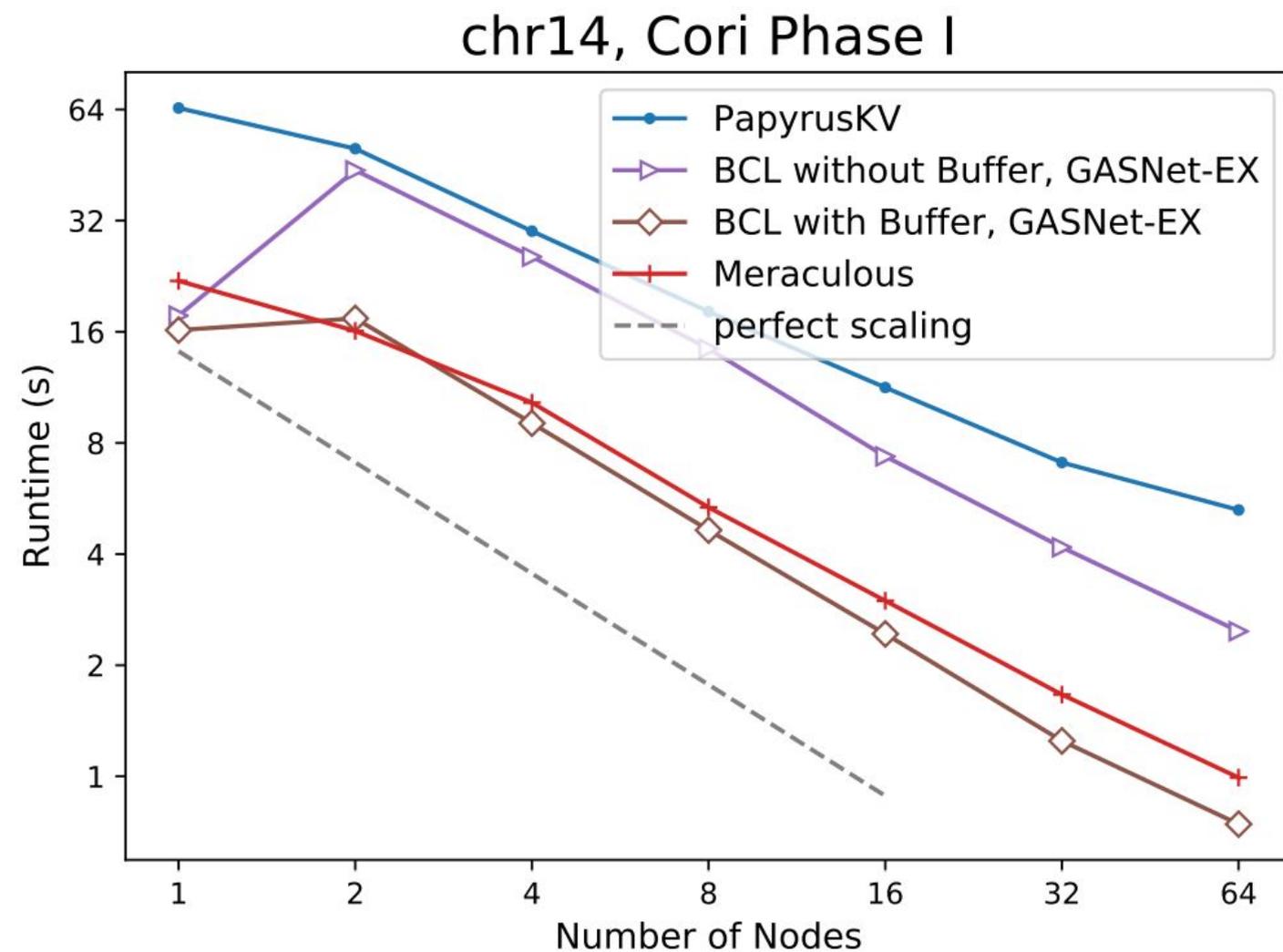


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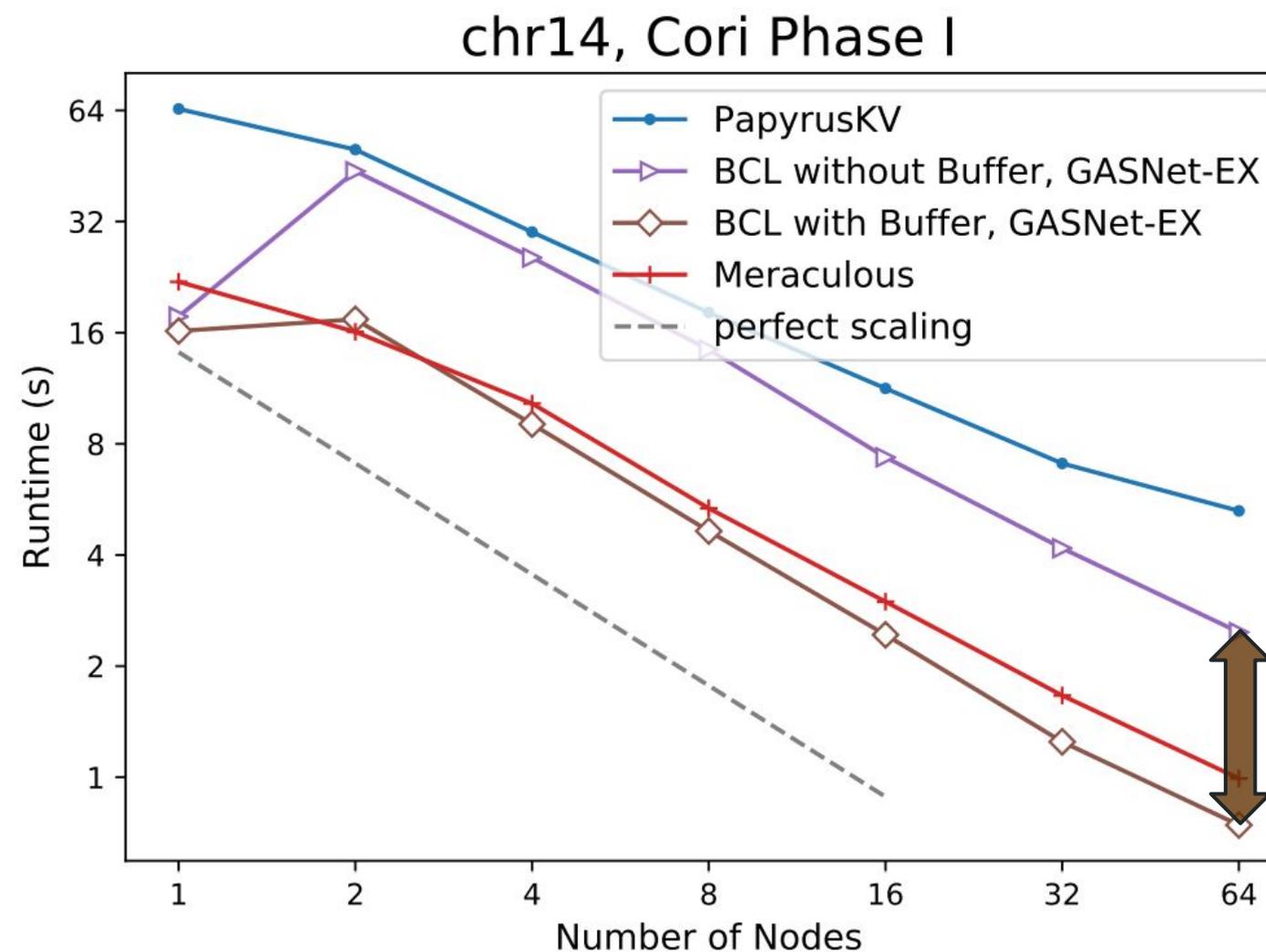
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# Genomics Benchmark

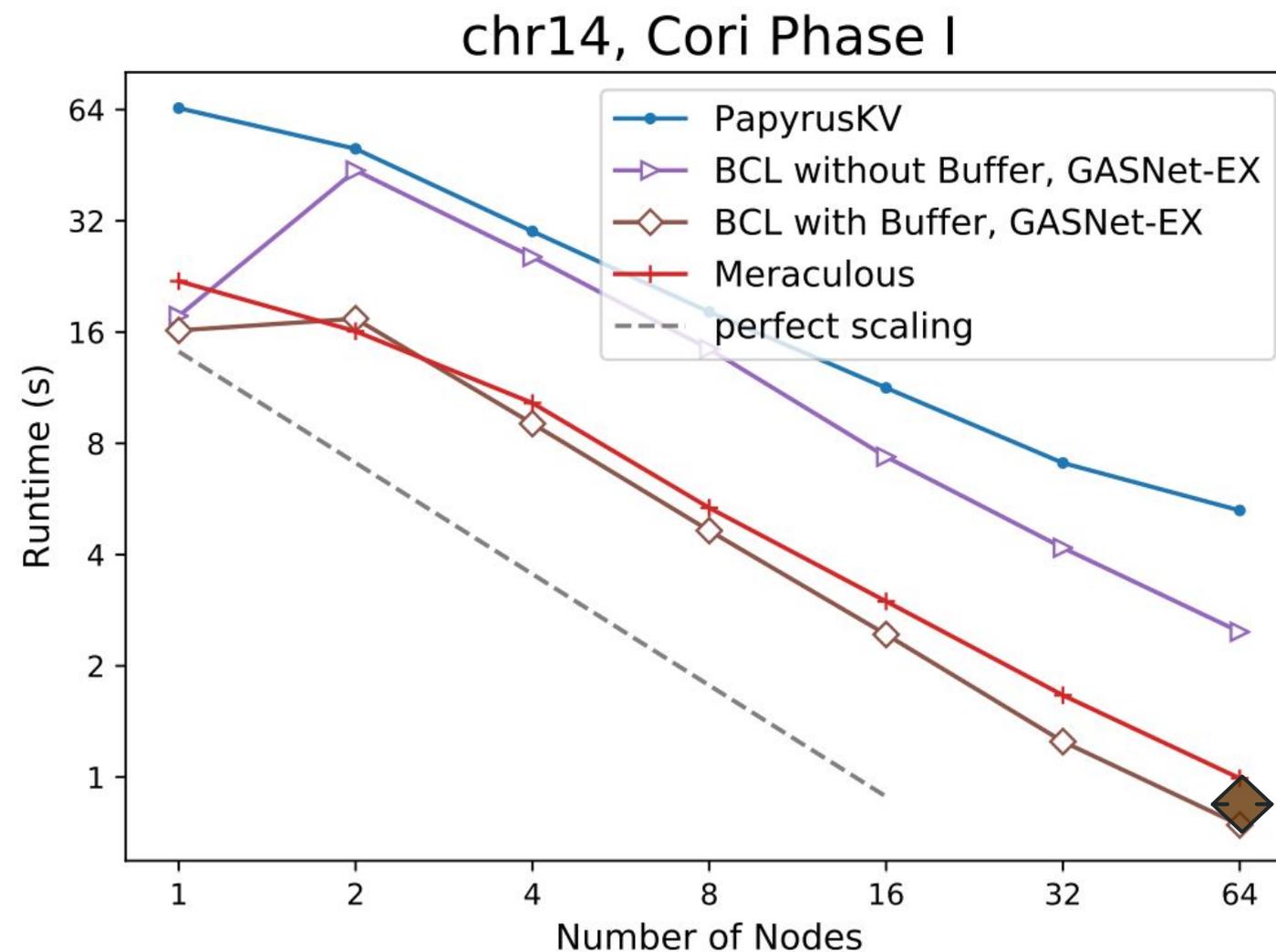


# Genomics Benchmark



**3.7x Improvement  
with Aggregator**

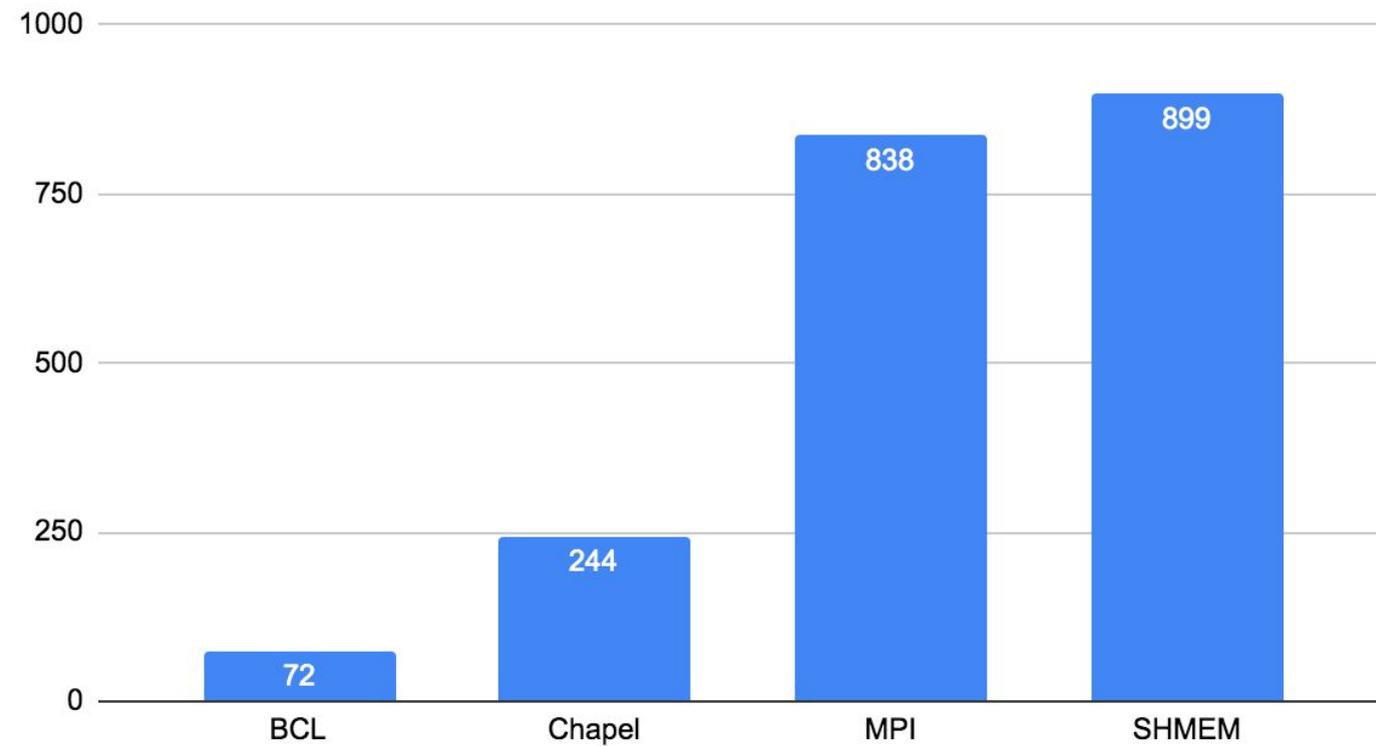
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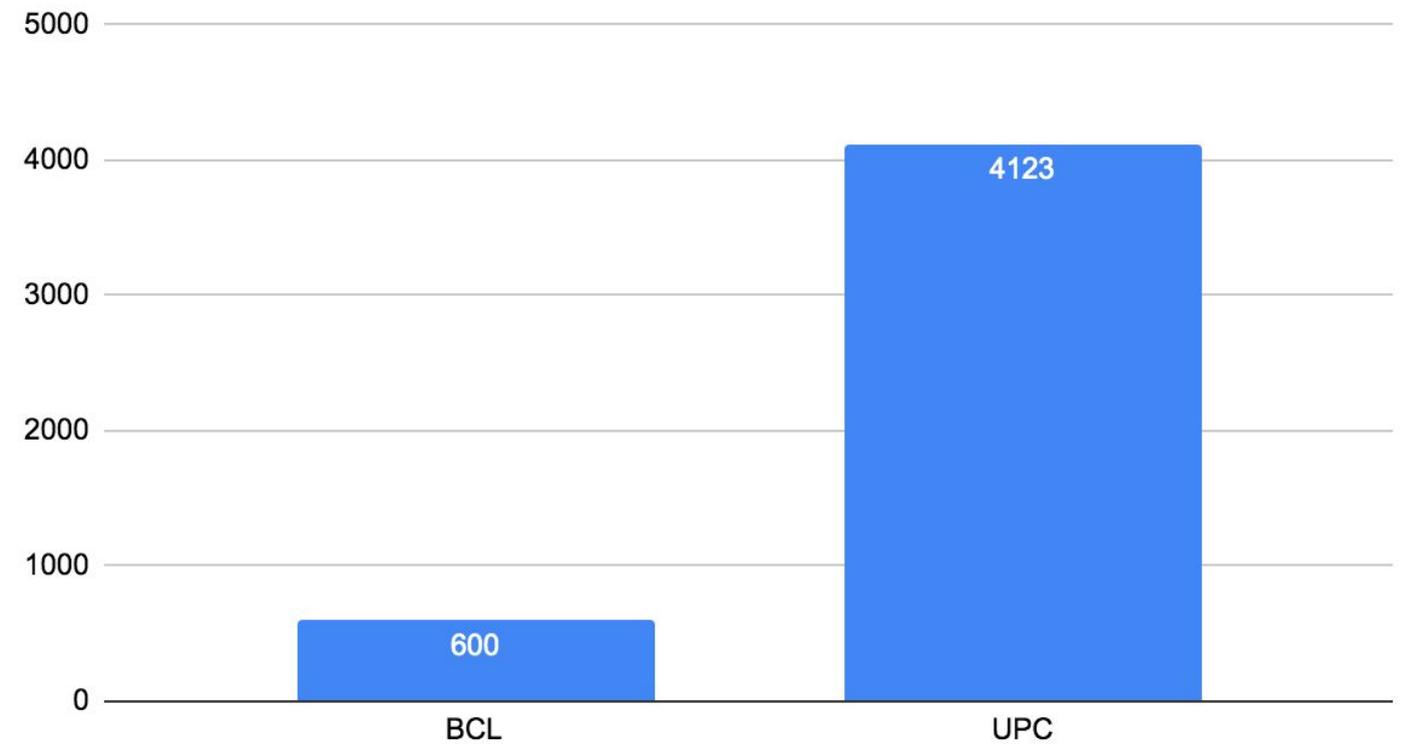
**Match Perf. of  
Expert-Tuned Impl.**

# Comparison: Lines of Code

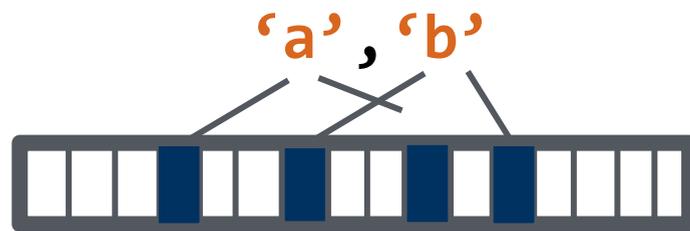
ISx Bucket Sort, Lines of Code



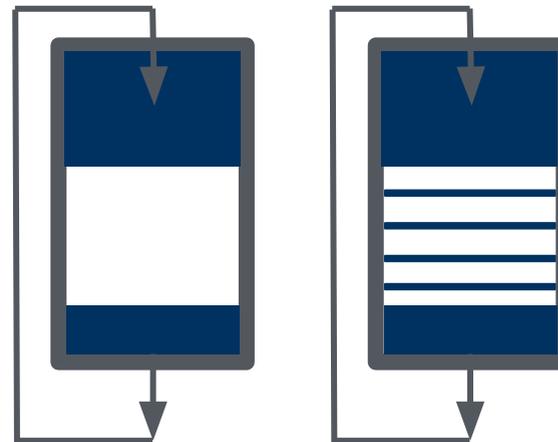
Meraculous, Lines of Code



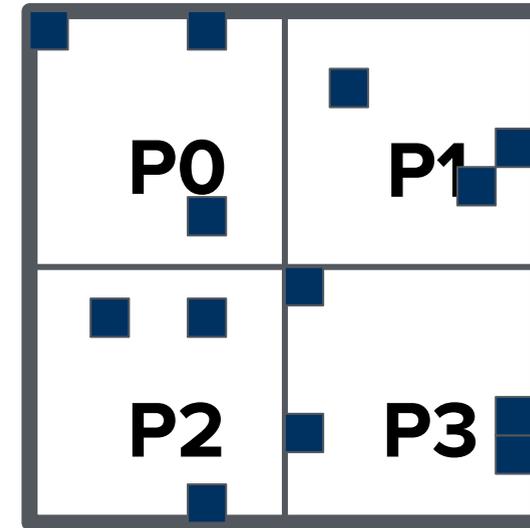
# Some Data Structures We've Worked On



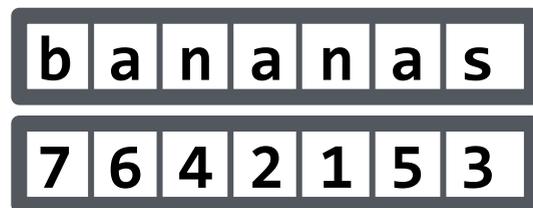
Bloom Filters



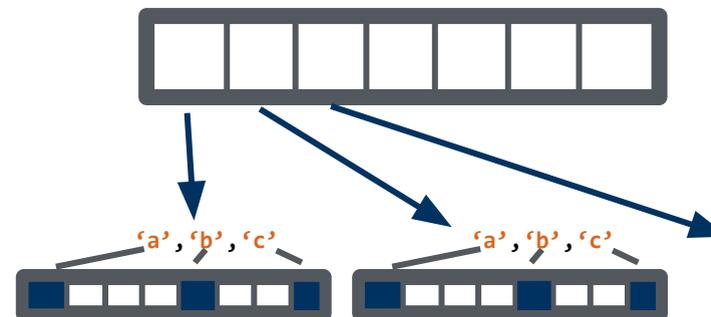
Queues



Dense and Sparse Matrices



Suffix Arrays

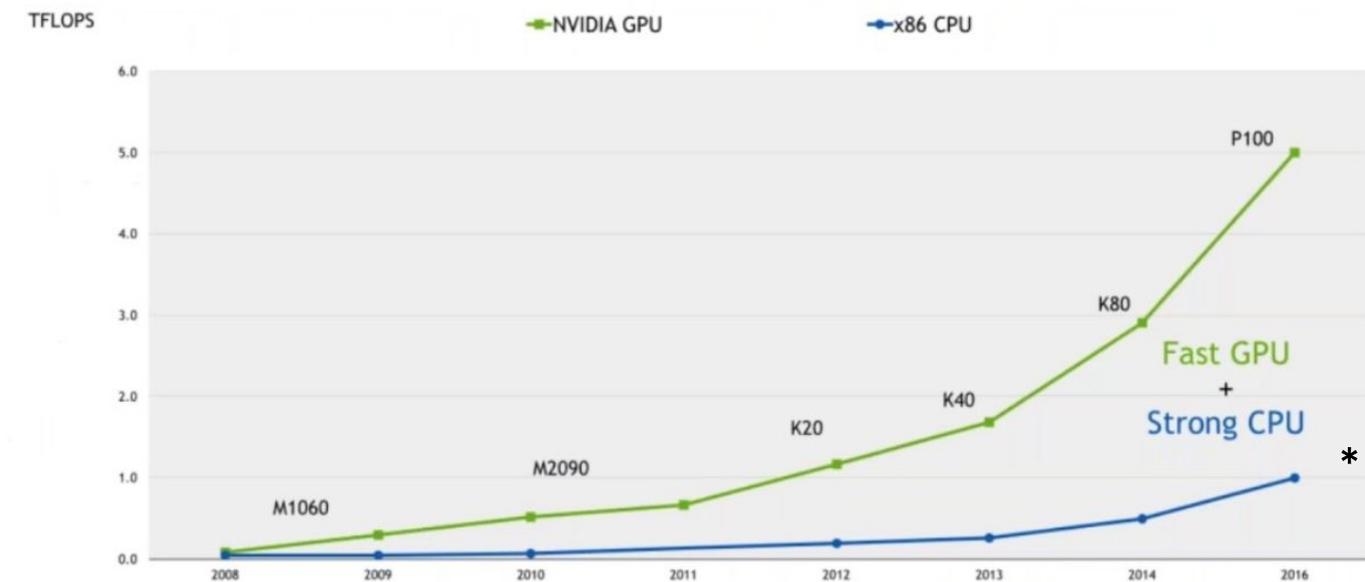
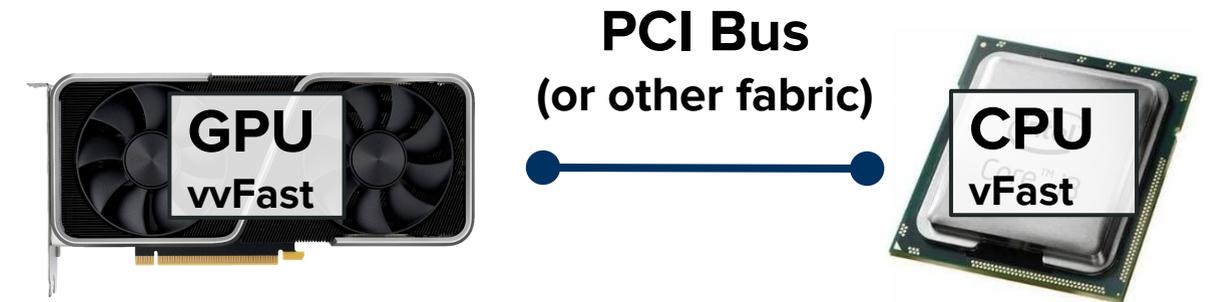


Hash Tables

# PGAS on GPUs

# GPUs as a First-Class Computing Resource

- **GPUs** play an important role in modern large-scale computing systems
- **All three** DOE exascale systems **will use GPUs**
- **~10x** more compute, BW

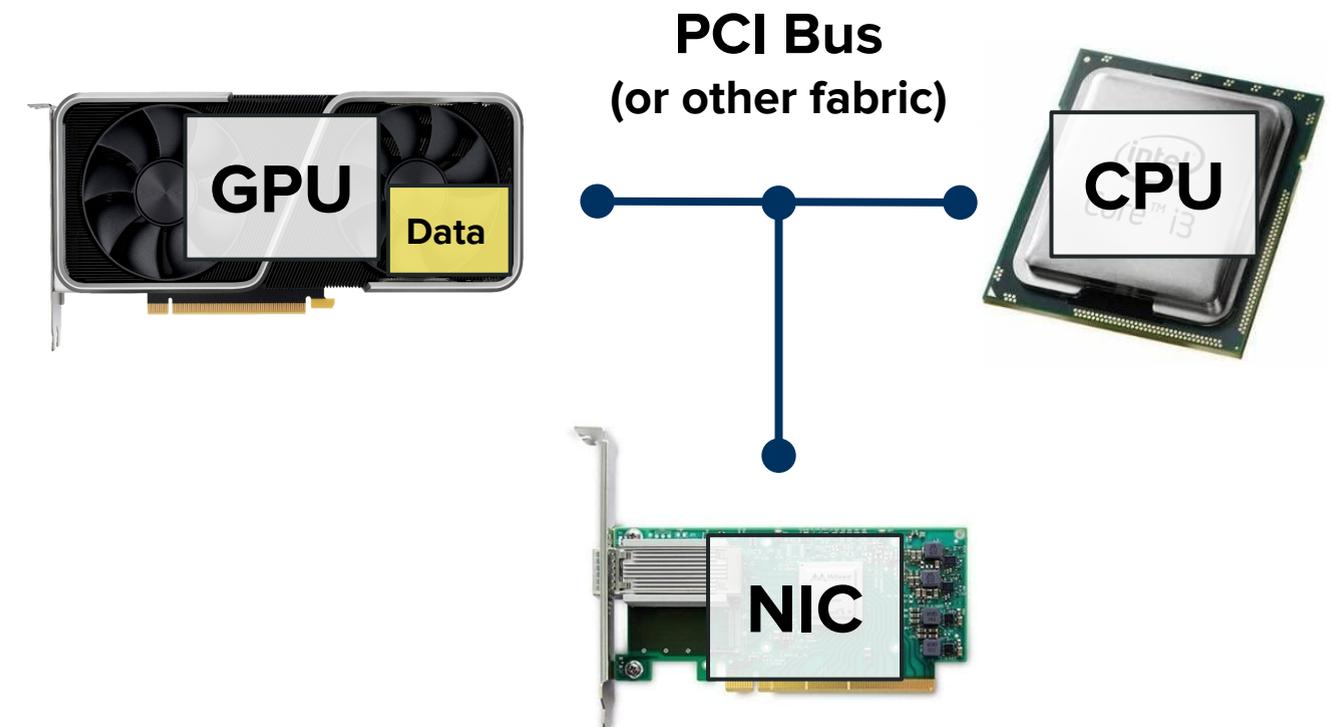


\* John Barco, Nvidia. <https://youtu.be/wvk9zYbOmYc>

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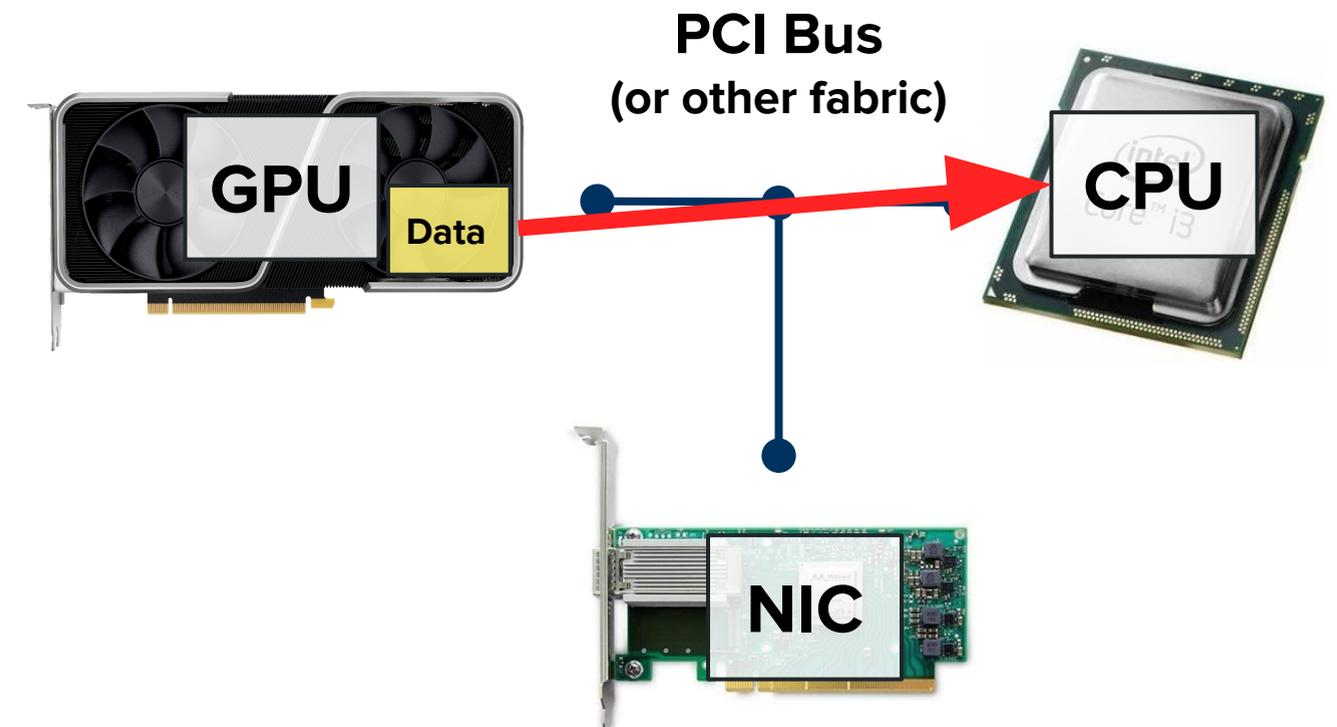
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- 1) Direct GPU access to **Infiniband** allows **GPU-to-GPU** network transfers
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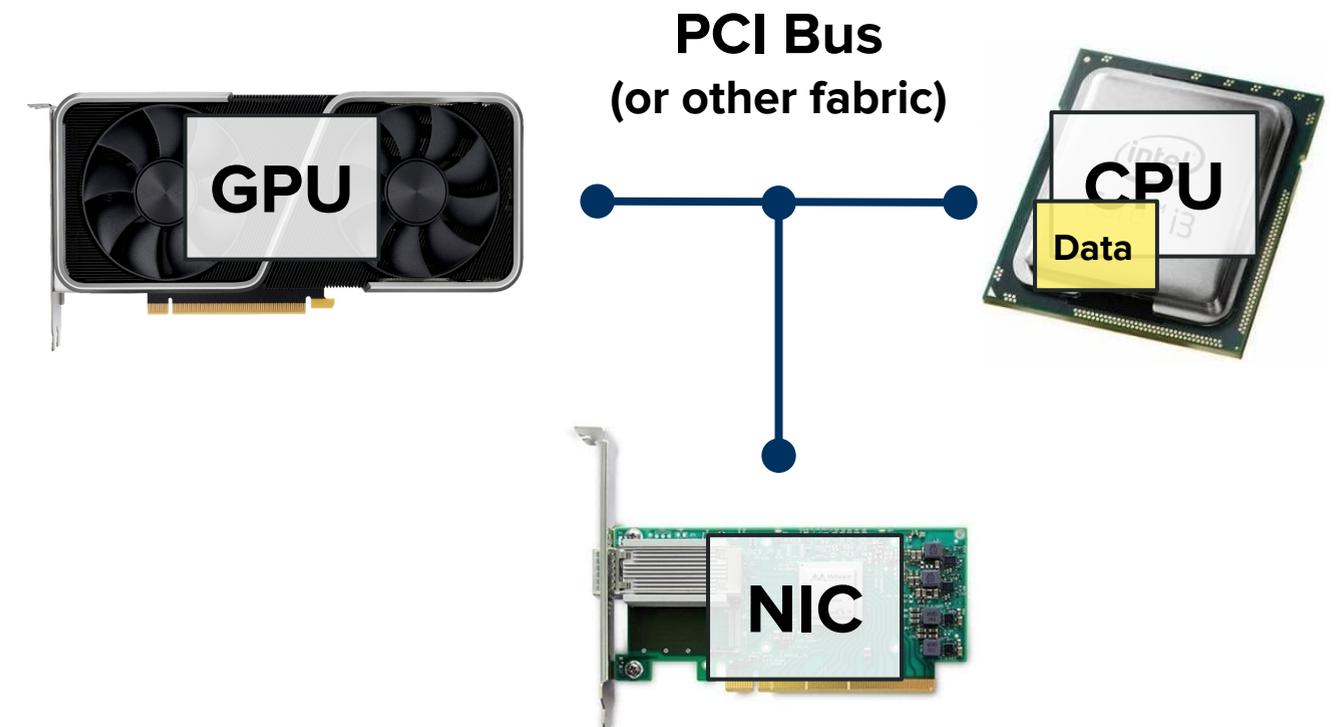
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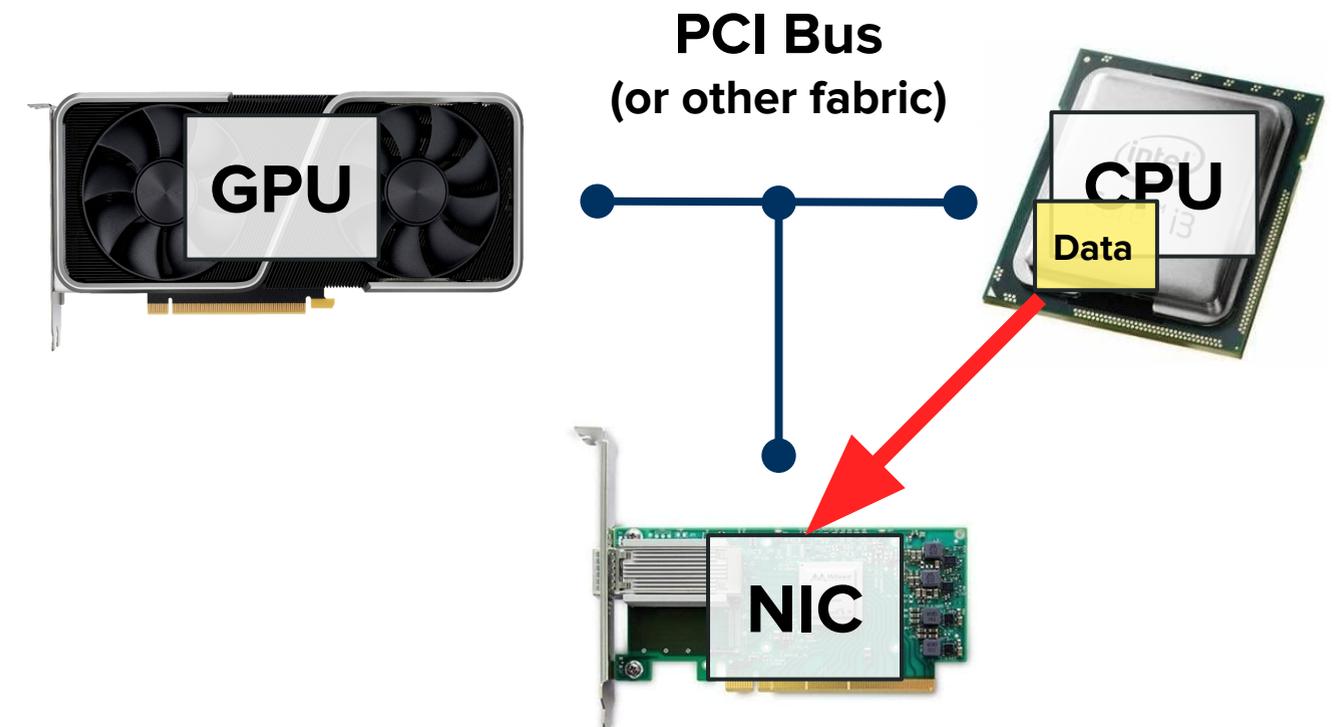
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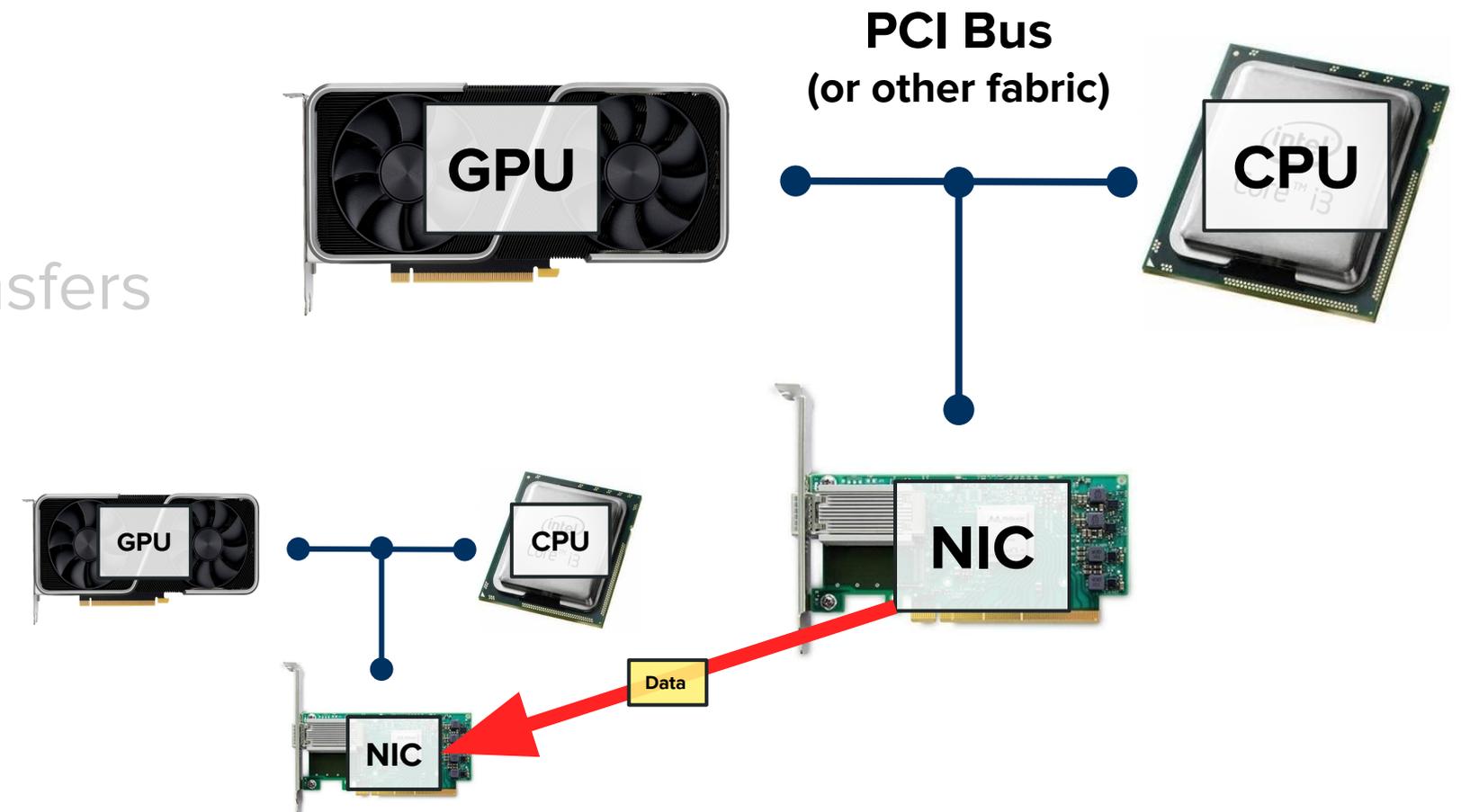
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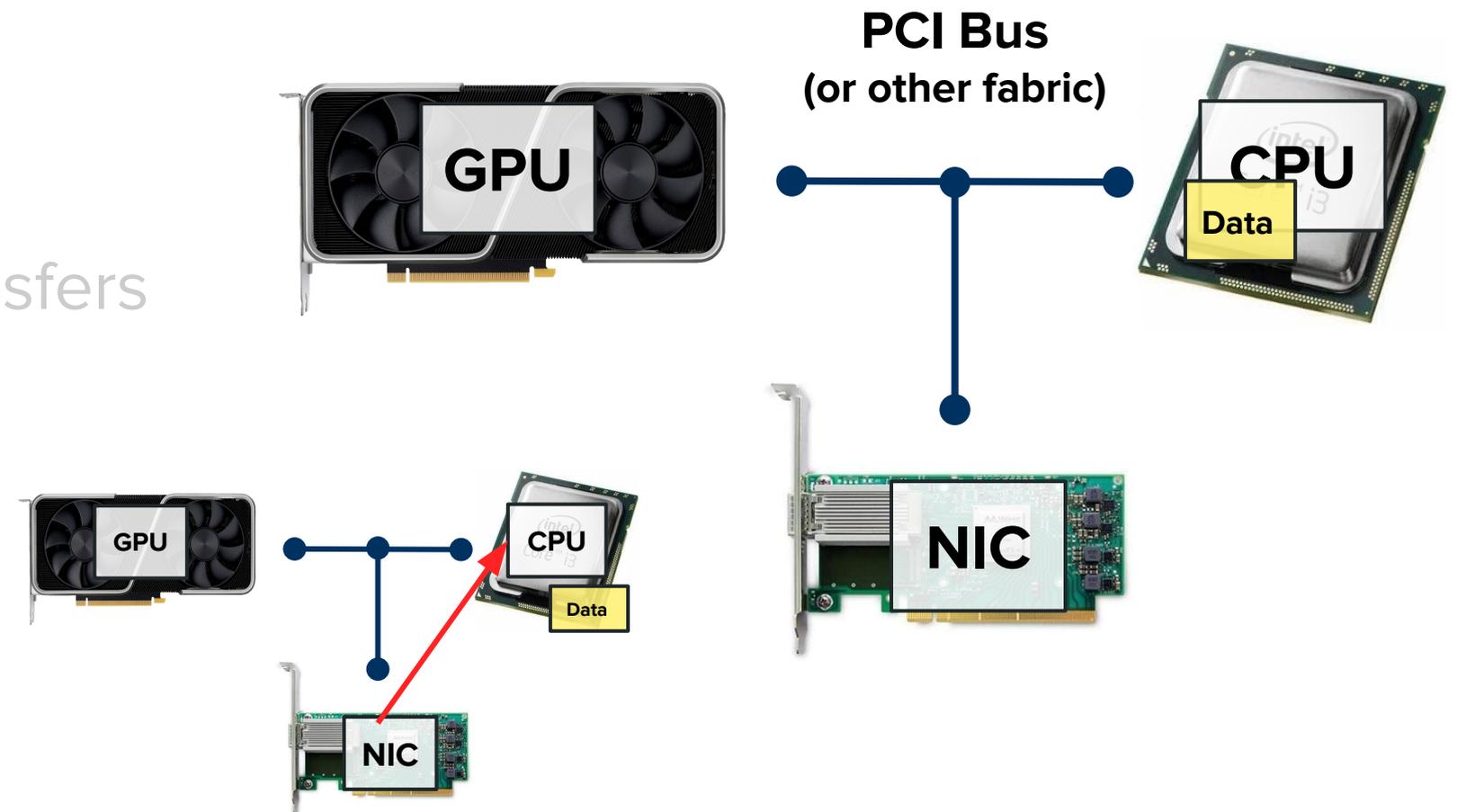
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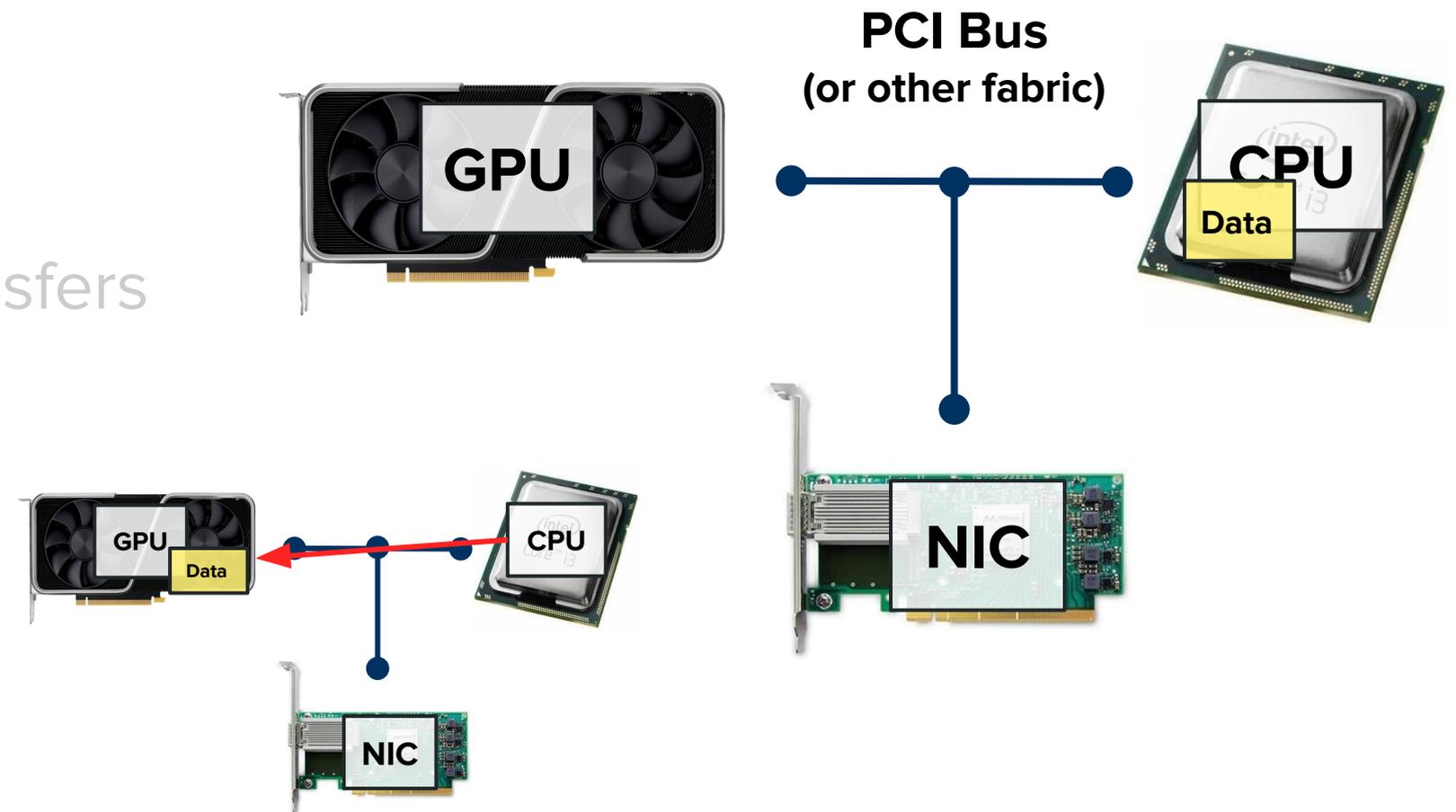
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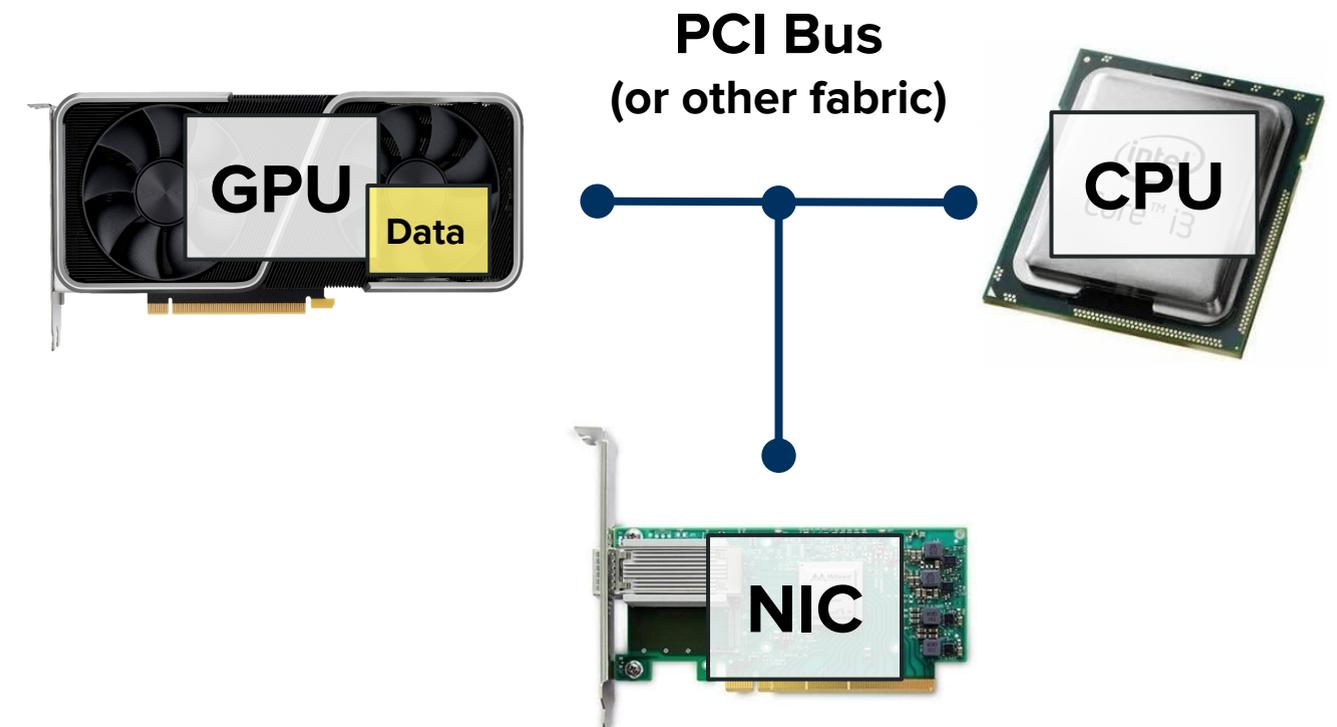
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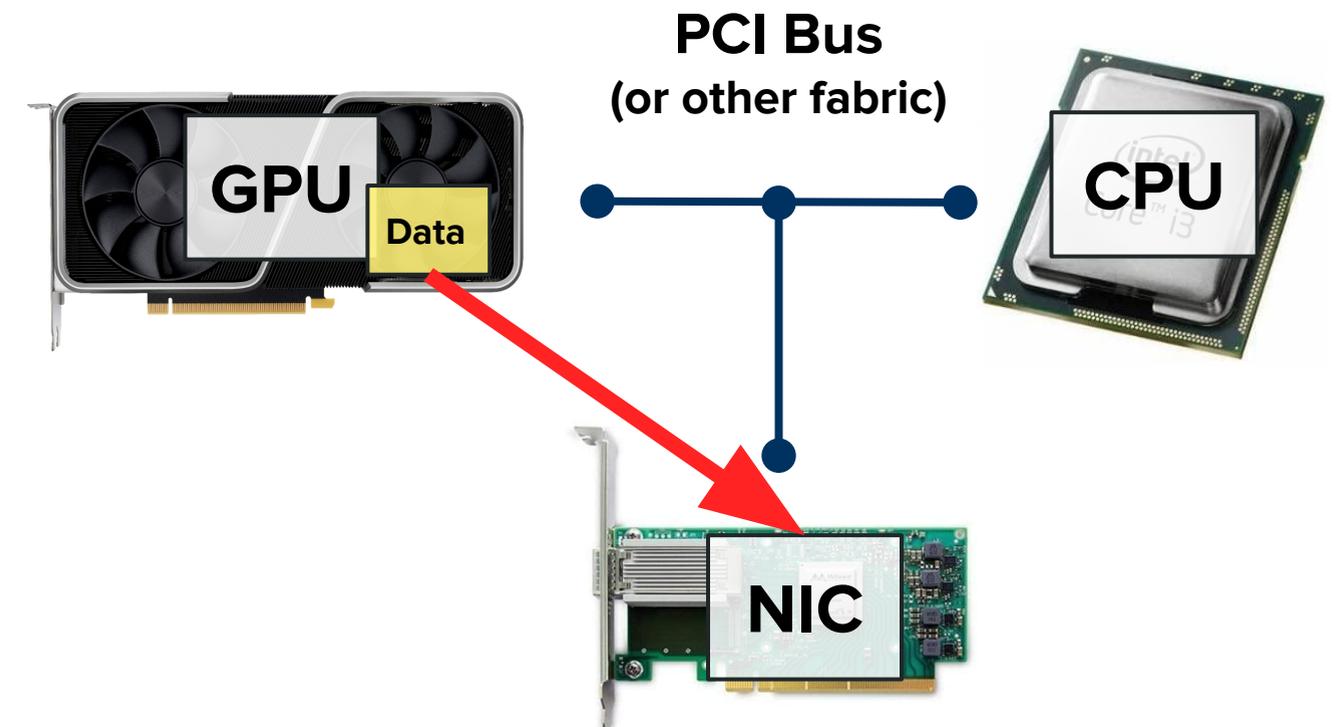
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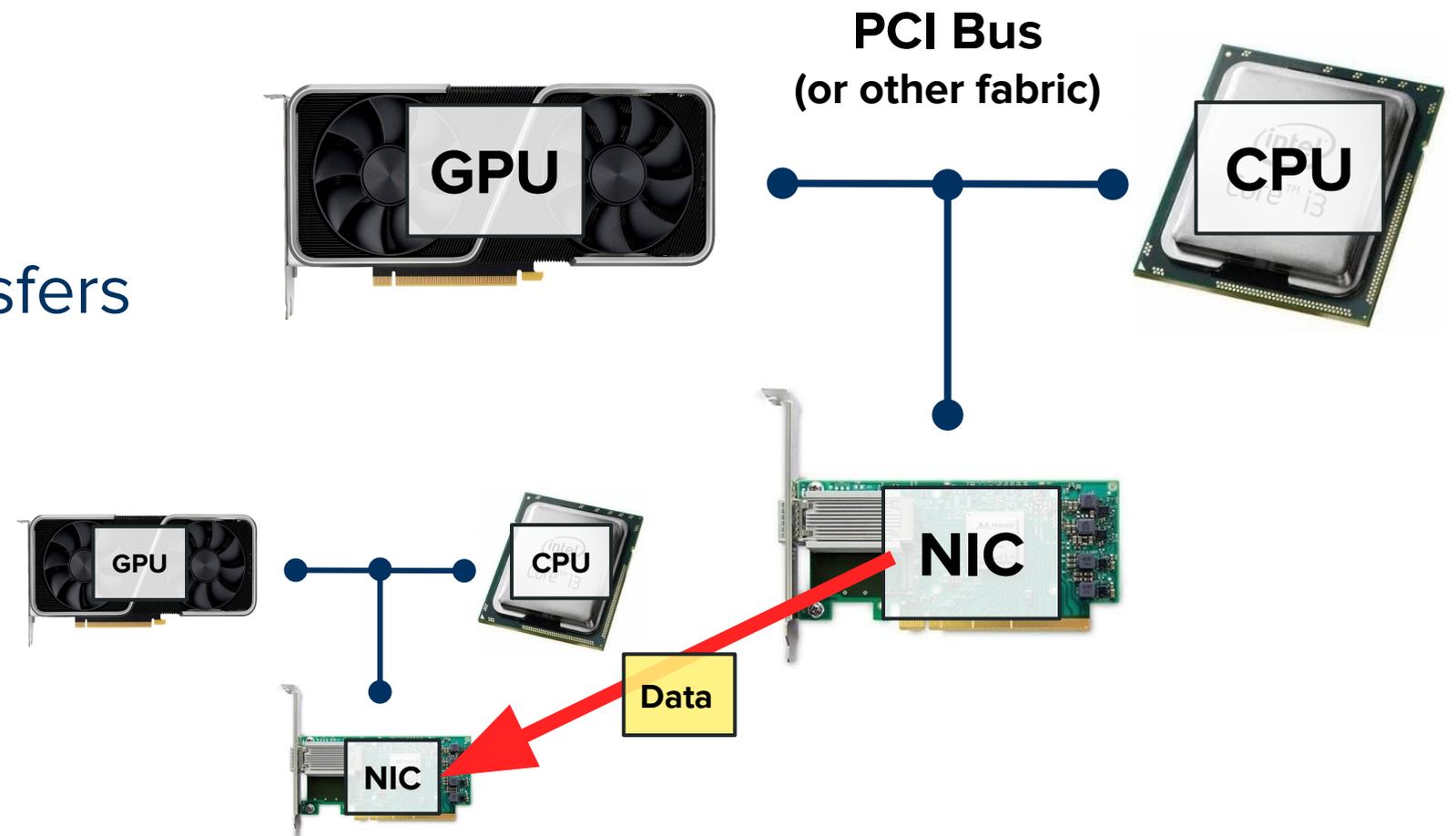


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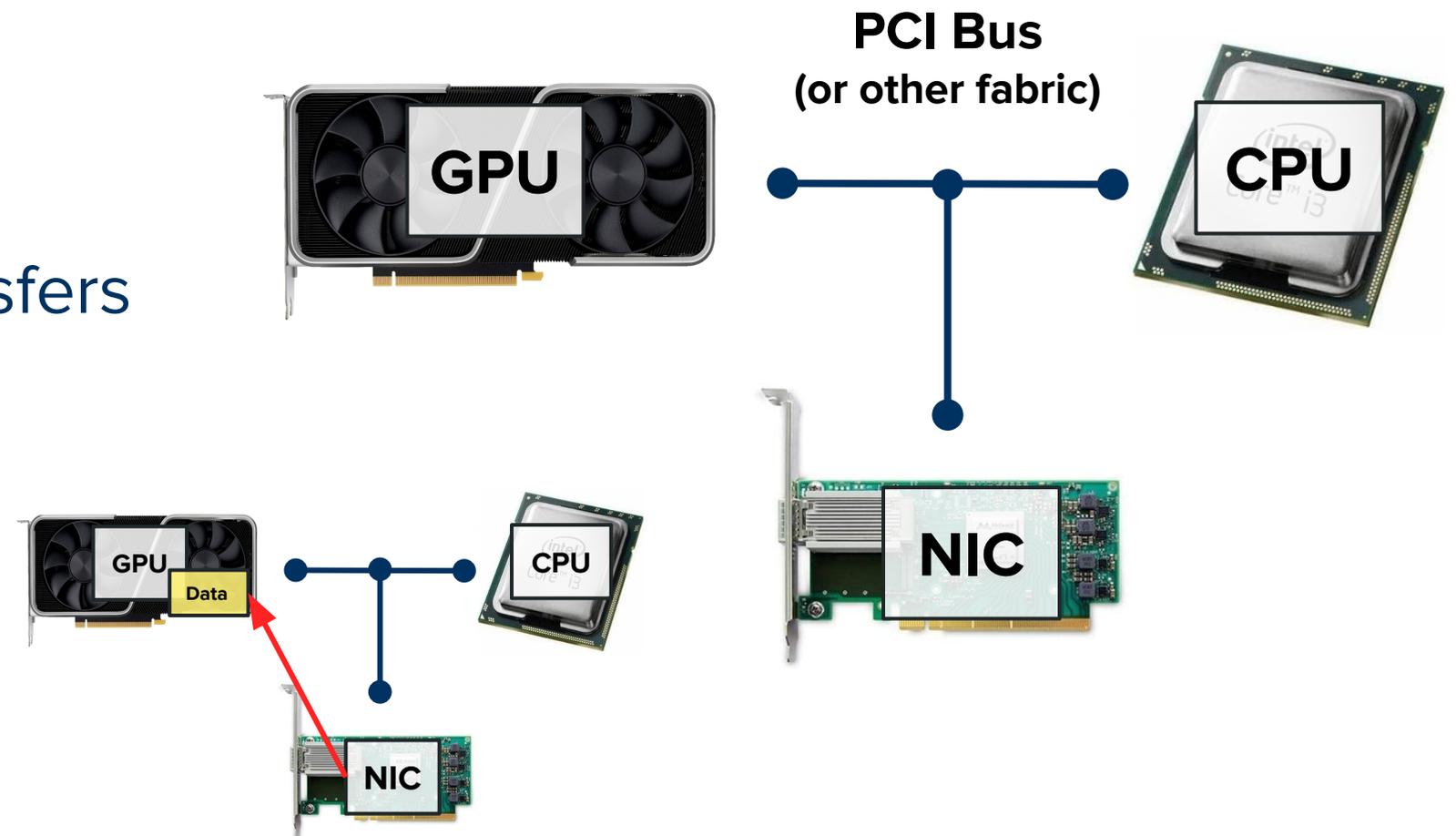


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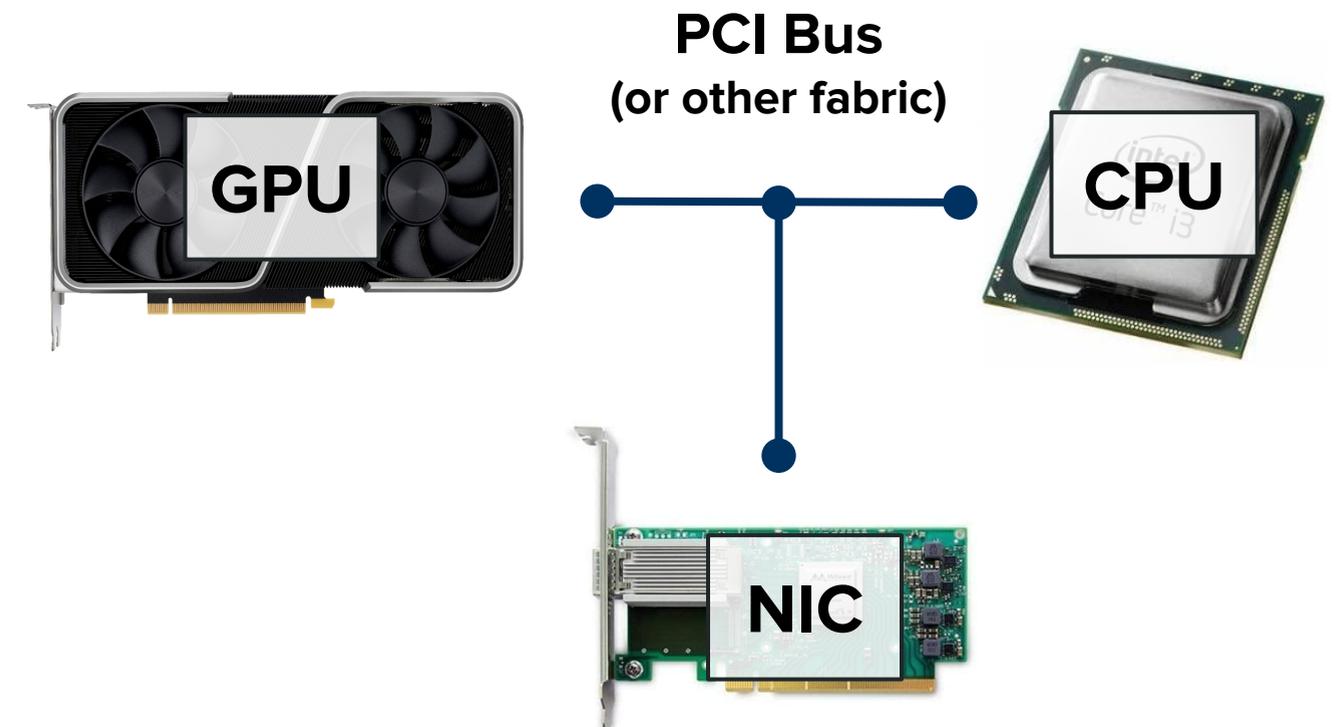
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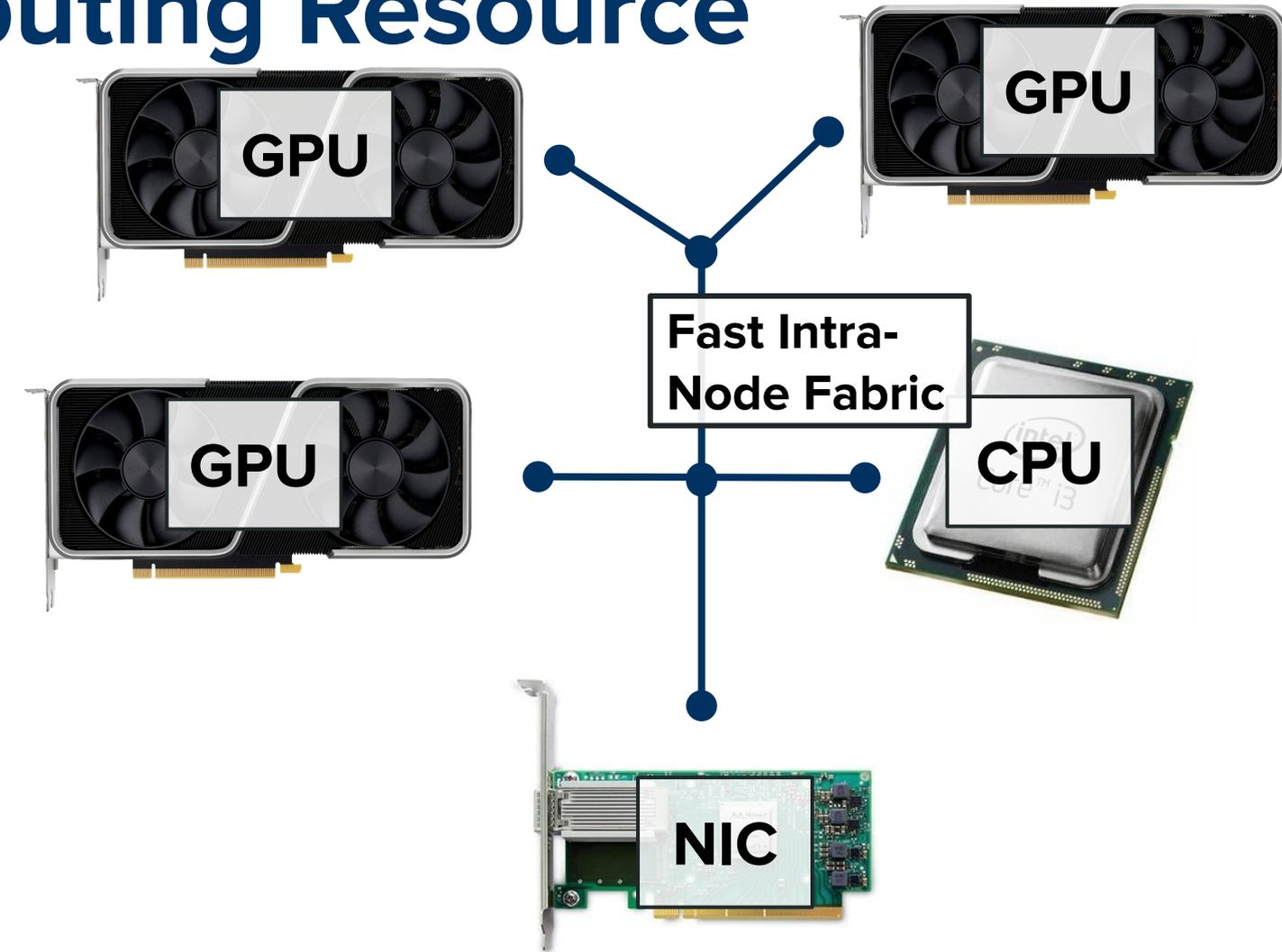
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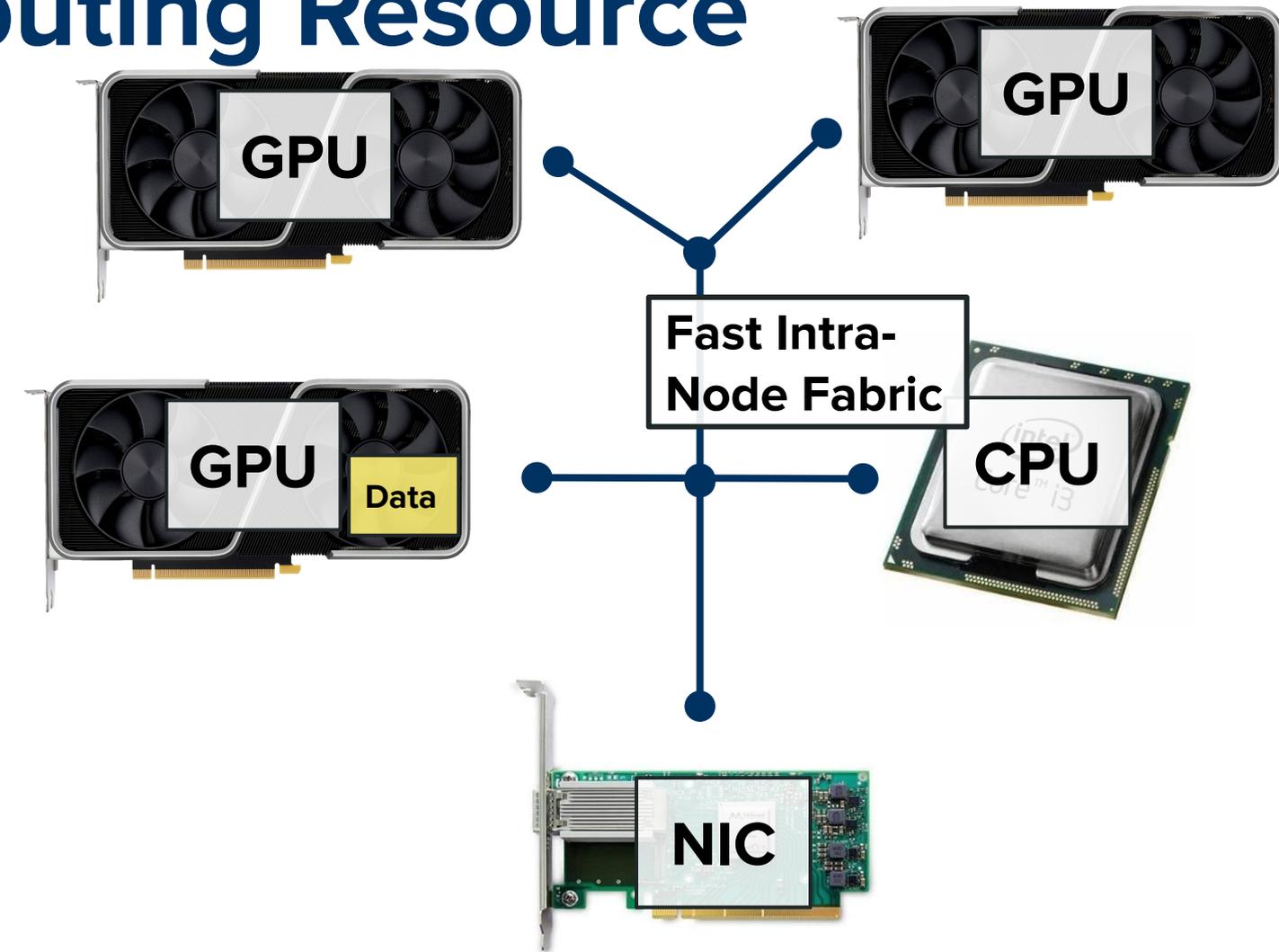
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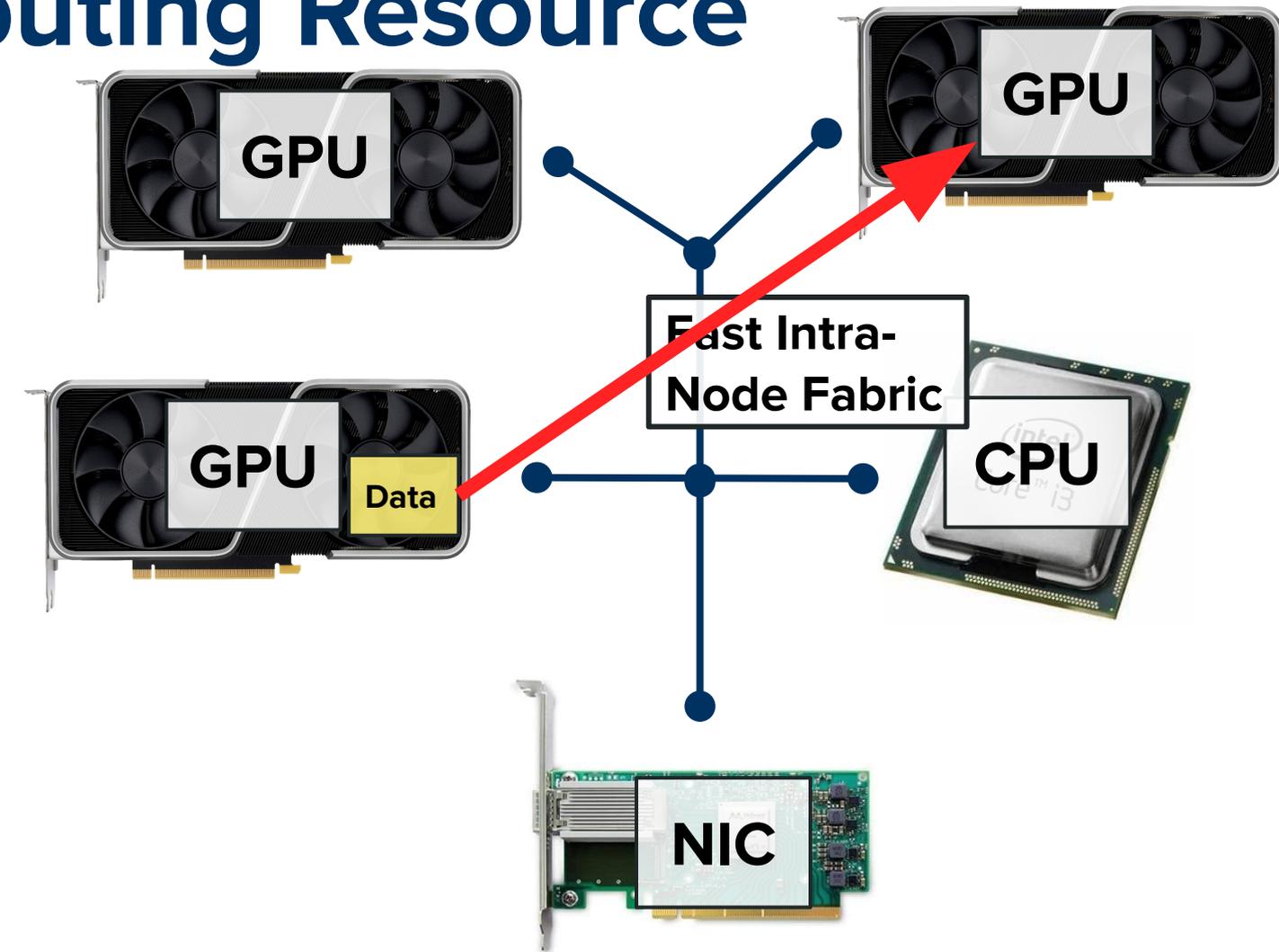
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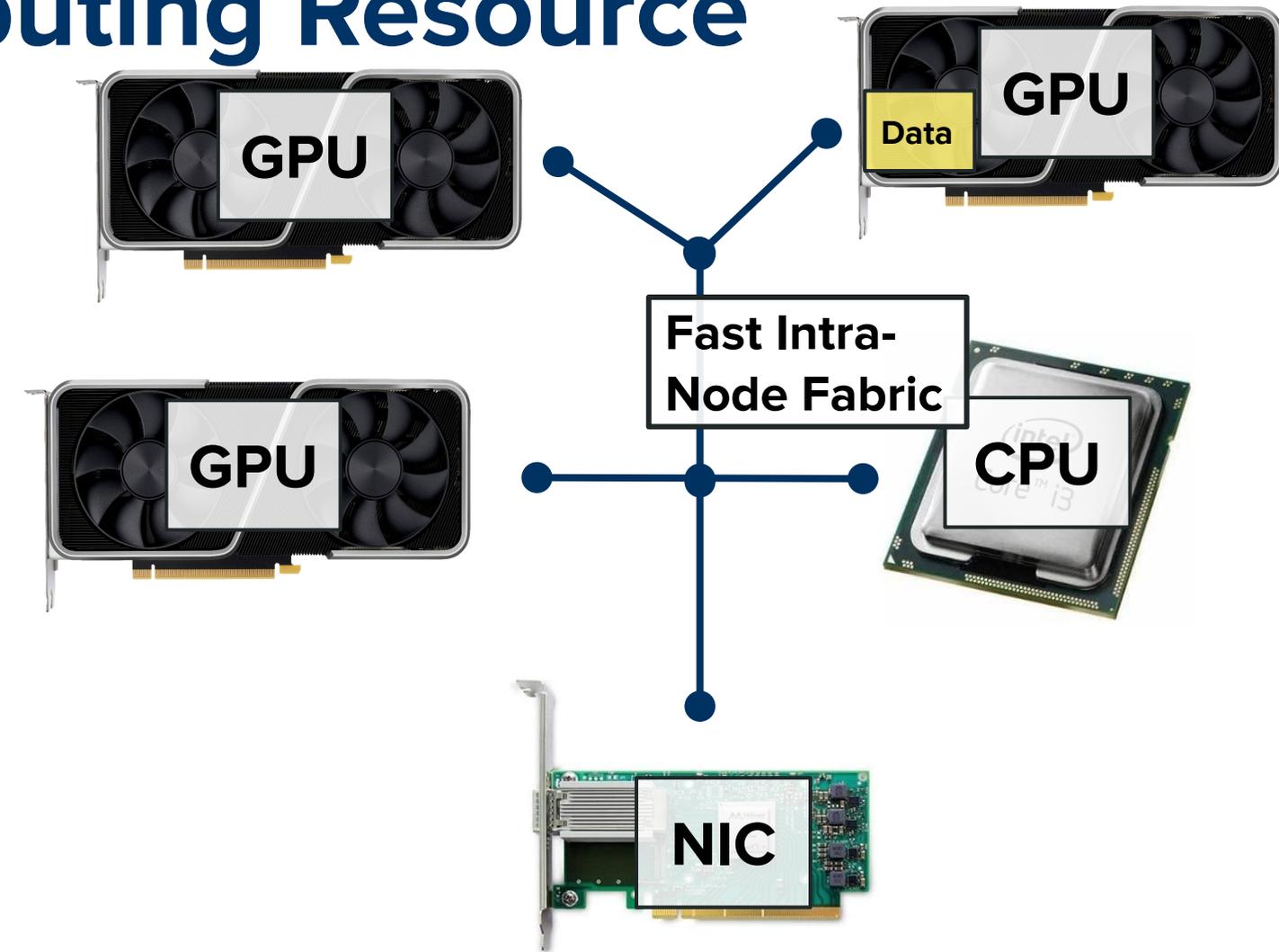
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# GPU Communication Libraries

- **Communication libraries** offering increasing support for GPU-to-GPU transfers
- Currently **only PGAS-based libraries** offer **GPU-initiated** communication
- **NVSHMEM** will utilize both **GPUDirect RDMA** and **NVLink**

CUDA-Aware MPI

MPI

GASNet-EX  
Memory Kinds

GASNet-EX



NVSHMEM



ROC\_SHMEM



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MPI

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Memory Kinds

GASNet-EX



NVSHMEM



NVIDIA

ROC\_SHMEM

AMD

# Remote Pointer Types

## CPU Remote Pointer

```
BCL::GlobalPtr<int> ptr = nullptr;

if (BCL::rank() == 0) {
    ptr = BCL::alloc<int>(BCL::nprocs());
}

ptr = BCL::broadcast(ptr, 0);

ptr[BCL::rank()] = BCL::rank();
```

# Remote Pointer Types

## CPU Remote Pointer

```
BCL::Glob
```

```
if (BCL::  
    ptr = BCL::  
}
```

```
ptr = BCL
```

```
ptr[BCL::
```

## Remote GPU Pointer

```
BCL::cuda::ptr<int> ptr = nullptr;
```

```
if (BCL::rank() == 0) {  
    ptr = BCL::cuda::alloc<int>(BCL::nprocs());  
}
```

```
ptr = BCL::broadcast(ptr, 0);
```

```
ptr[BCL::rank()] = BCL::rank();
```

# Remote Pointer Types

## CPU Remote

```
BCL::GlobalP  
  
if (BCL::ran  
    ptr = BCL:  
}  
  
ptr = BCL::b  
  
ptr[BCL::ran
```

## Remote GPU Pointer (Accessing on GPU)

```
__global__ void kernel(BCL::cuda::ptr<int> ptr) {  
    size_t tid = ...;  
  
    ptr[tid] = tid;  
}  
  
...  
  
BCL::cuda::ptr<int> ptr = nullptr;  
  
if (BCL::rank() == 0) {  
    ptr = BCL::cuda::alloc<int>(BCL::nprocs());  
}  
  
ptr = BCL::broadcast(ptr, 0);  
  
if (BCL::rank() == 1) {  
    kernel<<<1, BCL::nprocs()>>>(ptr);  
}
```

# Remote Pointer Types for GPUs

## CPU Remote Pointer

```
template <typename T>
struct GlobalPtr {

    ...

private:
    size_t rank_;
    size_t offset_;
};
```

# Remote Pointer Types for GPUs

## CPU Remote Pointer

```
template <typename T>
struct GlobalPtr {
    ...

private:
    size_t rank_;
    size_t offset_;
};
```

```
void memcpy(void* dest,
            GlobalPtr<void> src,
            size_t n) {
    // Issue remote get operation to
    // copy `n` bytes from `src` to `dest`
    backend::remote_get(dest, src, n, ...);
}
```

# Remote Pointer Types for GPUs

## GPU Remote Pointer

```
template <typename T>
struct ptr {

    ...

private:
    size_t rank_;
    size_t offset_;
};
```

# Remote Pointer Types for GPUs

## GPU Remote Pointer

```
template <typename T>
struct ptr {
    ...

private:
    size_t rank_;
    size_t offset_;
};
```

```
__host__ __device__
void memcpy(void* dest,
            cuda::ptr<void> src,
            size_t n) {
    // Issue remote get operation to
    // copy `n` bytes from `src` to `dest`
#ifdef __CUDA_ARCH__
    nvshmem_getmem(dest,
                  src.rptr(), n,
                  src.rank());
#else
    ...
#endif
}
```

# Remote Pointer Types for GPUs

## GPU Remote Pointer

```
template <typename T>
struct ptr {
    ...

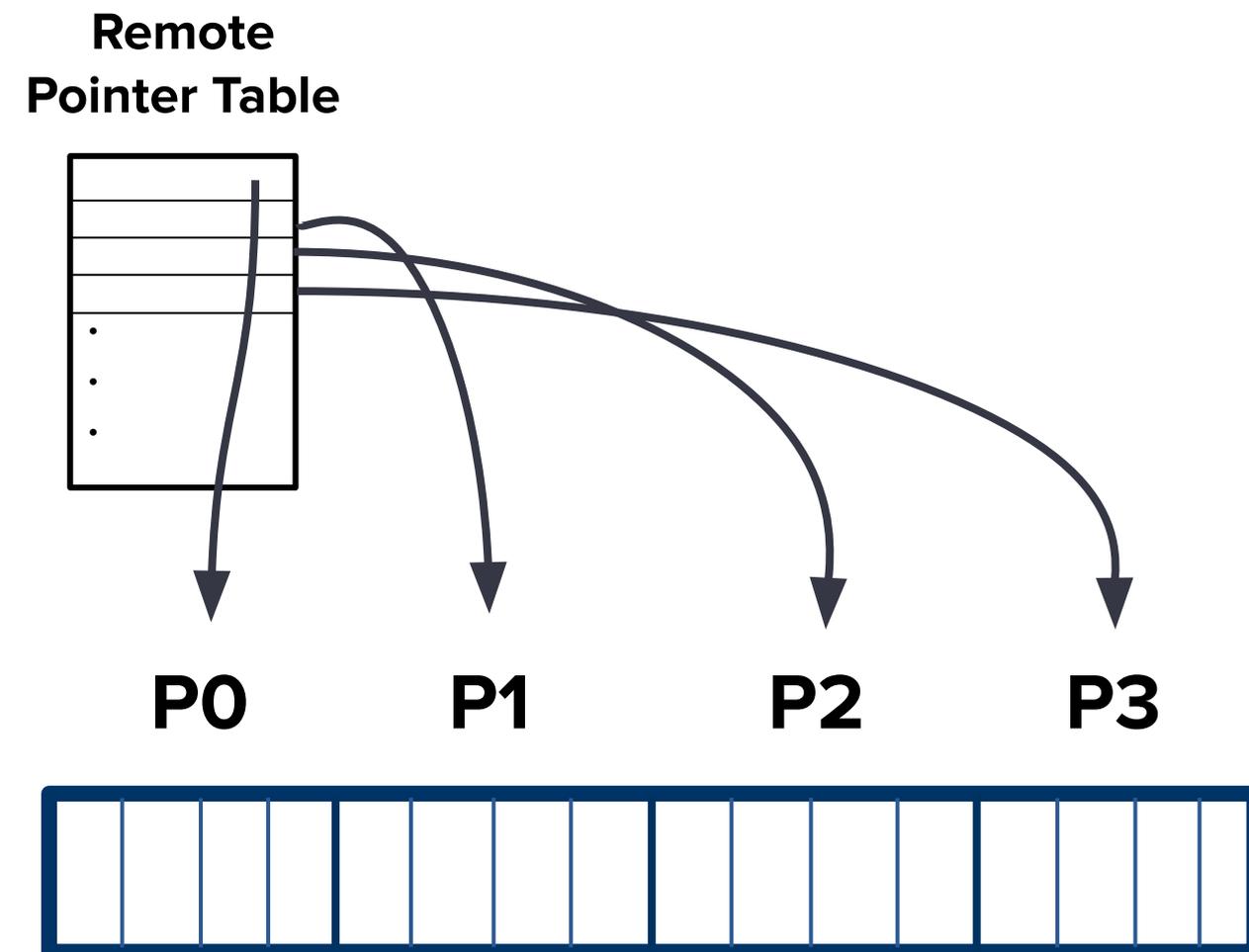
private:
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```
__host__ __device__
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#else
    ...
#endif
}
```

On CPU, necessary to stage data if transferring to host (CPU) memory.

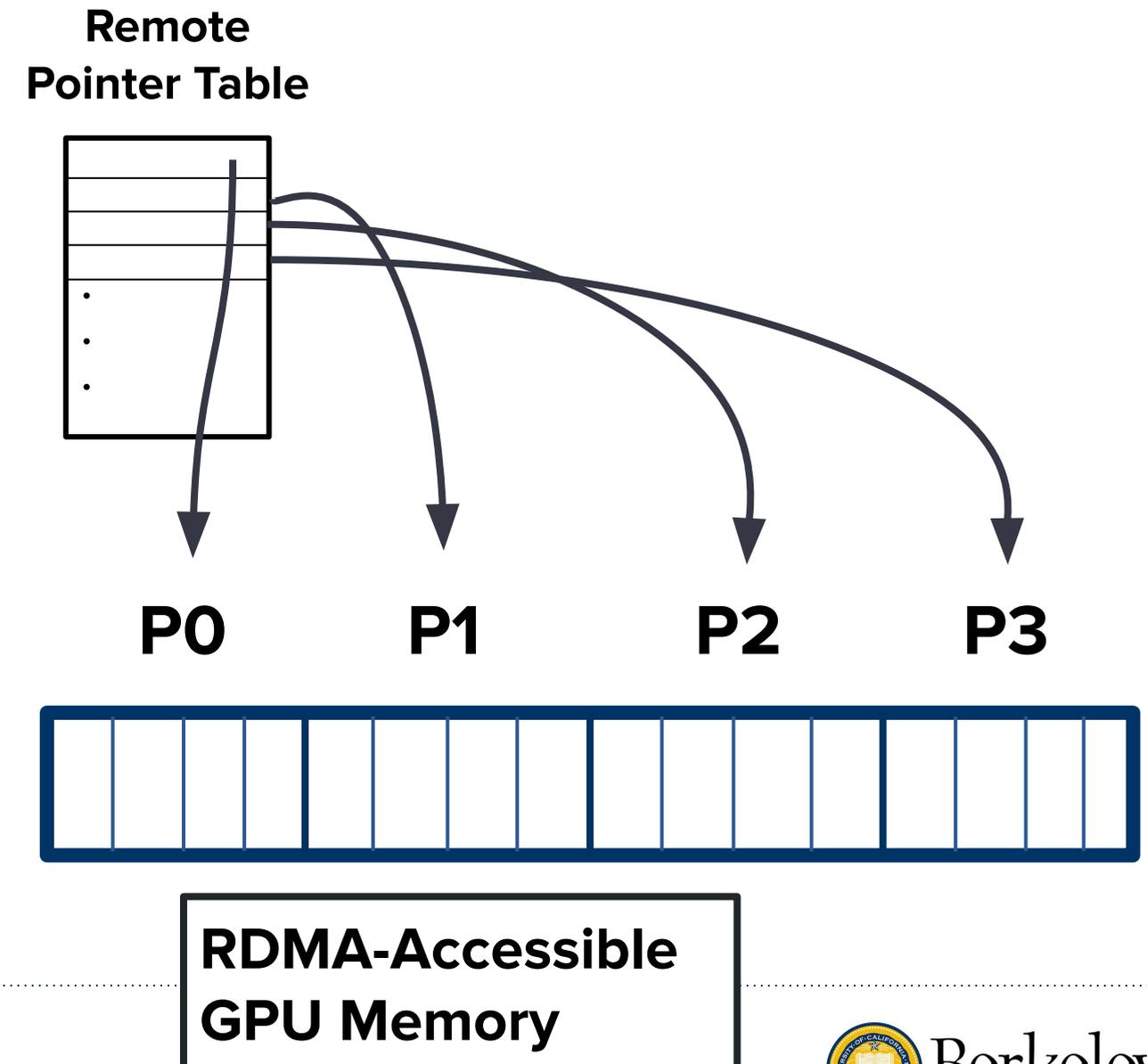
# Distributed Data Structures on GPUs

- Recall that **each process** needs a **table of pointers** to access data
- To implement **GPU-side methods**, need **GPU-accessible** table
- Is this enough to implement **GPU-side data structure methods**?



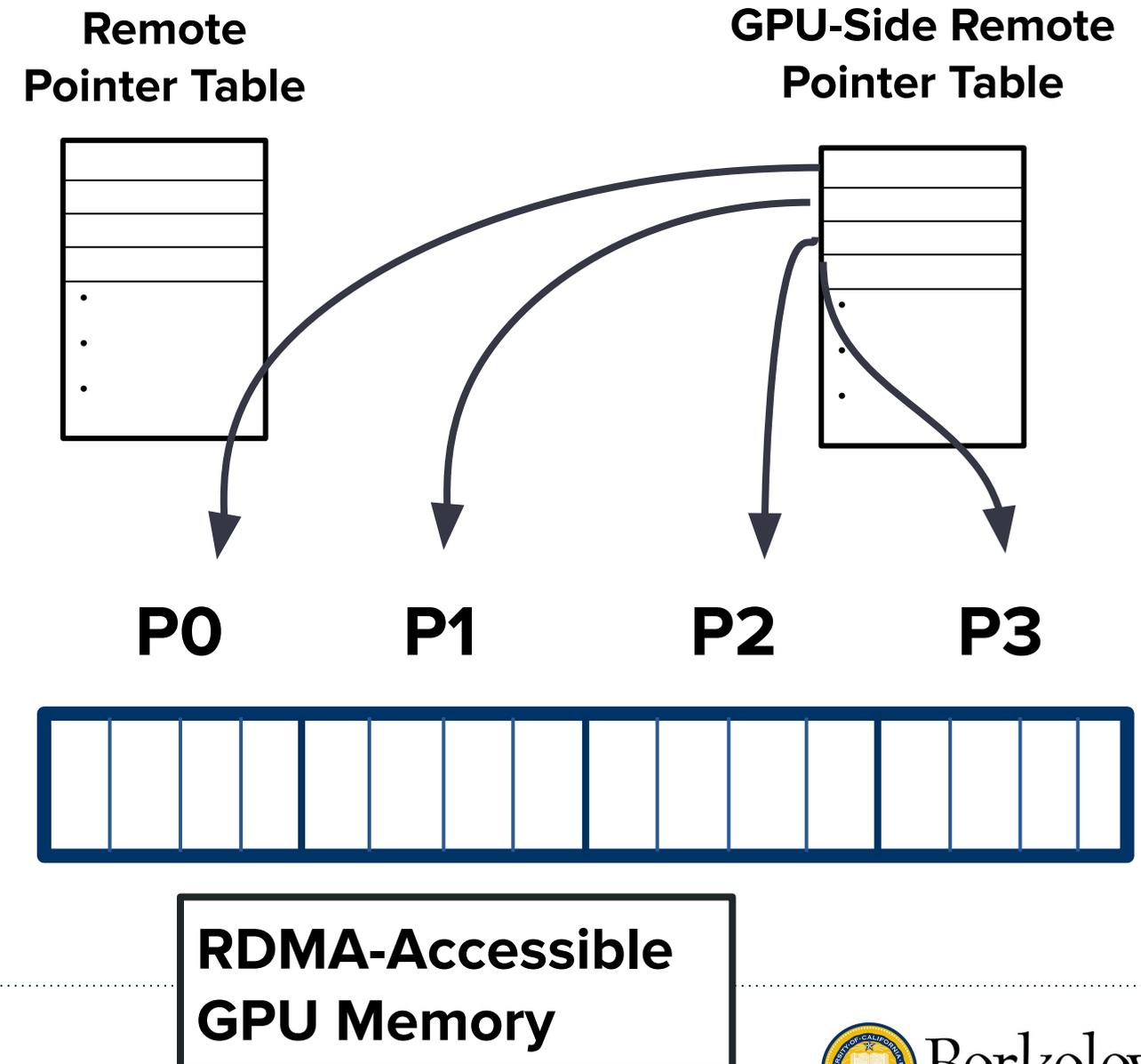
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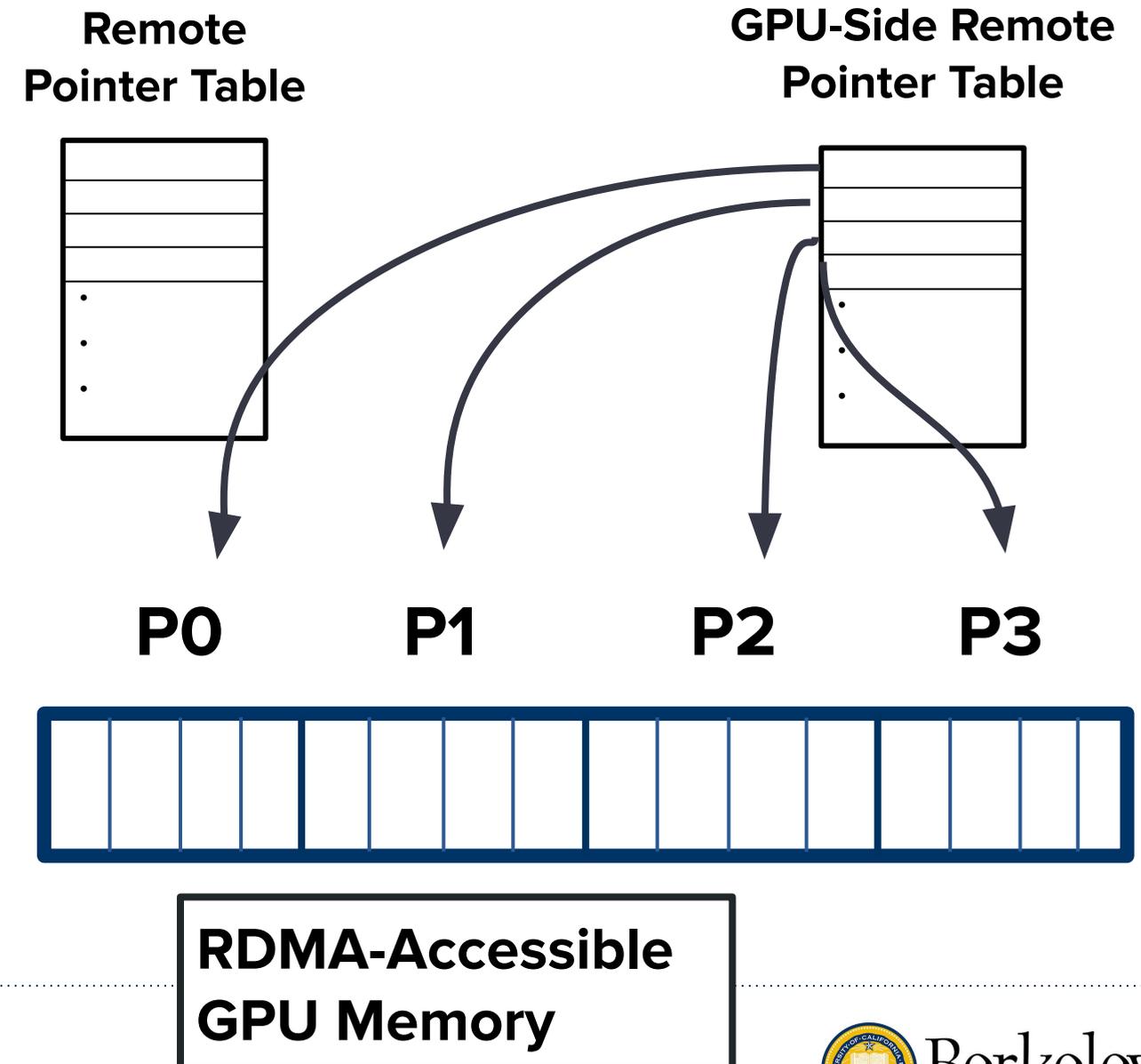
# Distributed Data Structures on GPUs

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# Distributed Data Structures on GPUs

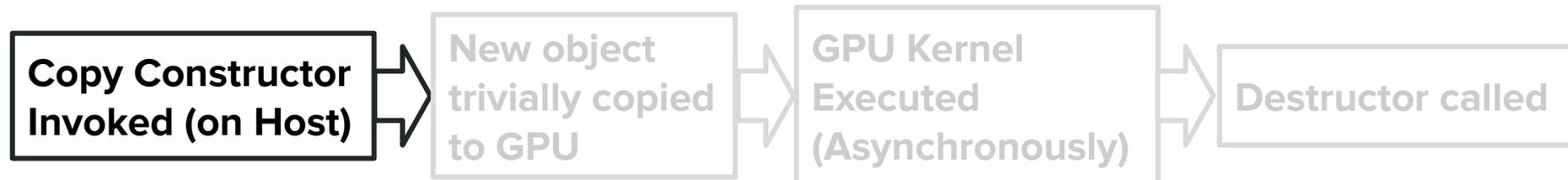
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# Passing Objects into CUDA Kernels

- Passing an **object by value** into a **CUDA kernel** results in a **copy**
- Object **likely destroyed** before kernel completes
- We need a **copy constructible** placeholder object

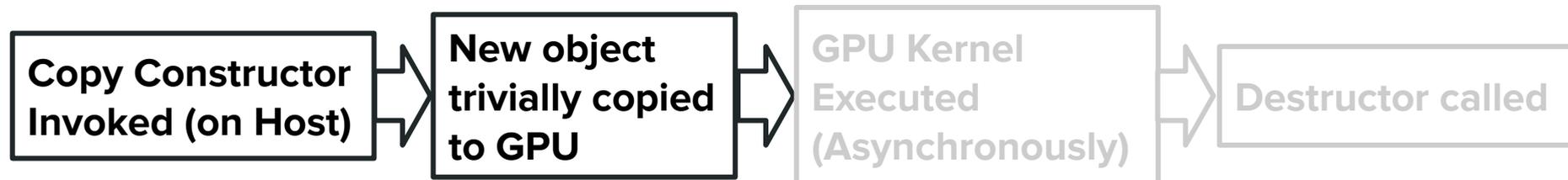
```
__global__  
void kernel(BCL::cuda::HashMap <int, int> map) {  
    size_t tid = ...;  
  
    size_t value = tid*2  
    map[tid] = value;  
}  
  
...  
BCL::cuda::HashMap<int, int> map(100);  
  
kernel<<<1, 100>>>(map);
```



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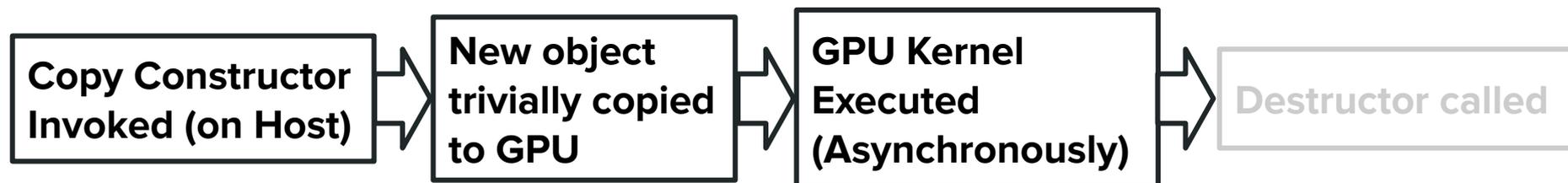
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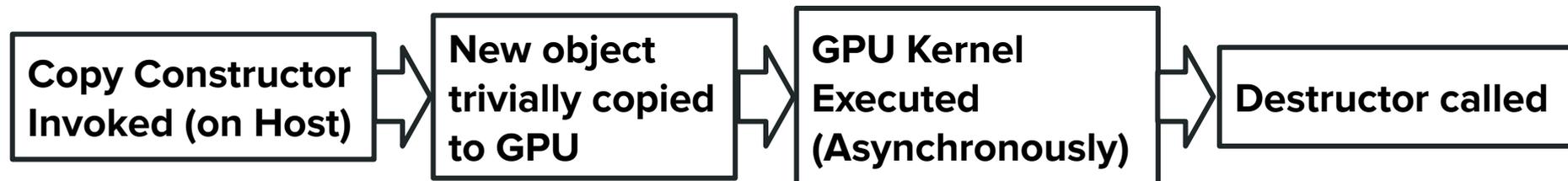
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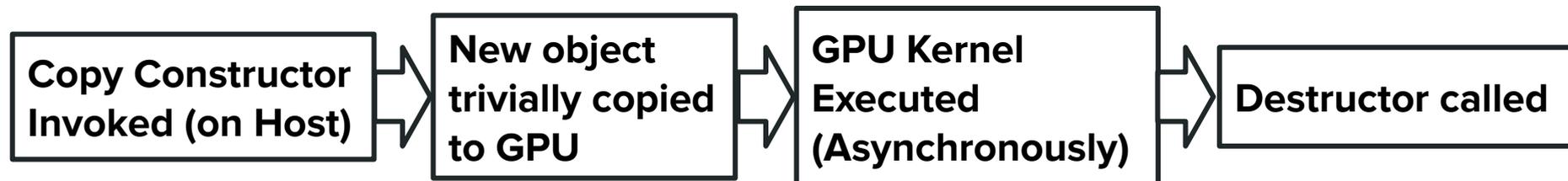
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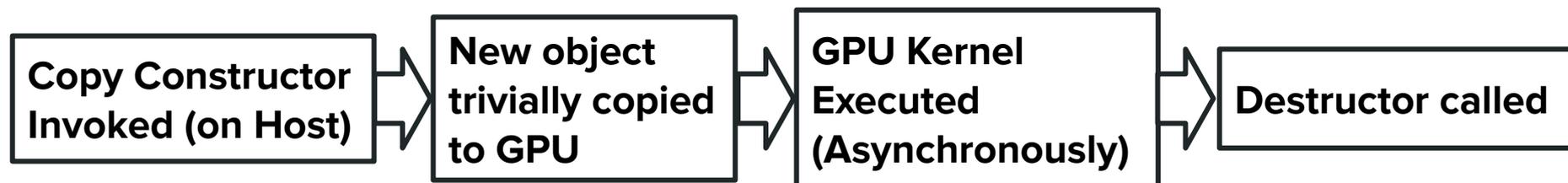
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void kernel(BCL::cuda::HashMap <int, int> map) {  
    size_t tid = ...;  
  
    size_t value = tid*2  
    map[tid] = value;  
}  
  
...  
BCL::cuda::HashMap<int, int> map(100);  
  
kernel<<<1, 100>>>(map);
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# Passing Objects into CUDA Kernels

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    size_t tid = ...;  
  
    size_t value = tid*2  
    map[tid] = value;  
}  
  
...  
BCL::cuda::HashMap<int, int> map(100);  
  
kernel<<<1, 100>>>(map);
```



# Using GPU Views within Kernels

- First create a `dmatrix_view` view object
- `dmatrix_view` has **O(1)** copy constructor (does not copy data)
- View can be used to access data on GPU

```
__global__  
void kernel(cuda::dmatrix_view<float> x_view) {  
    size_t tid = ...;  
  
    size_t i = tid / x.shape()[0];  
    size_t j = tid % x.shape()[0];  
  
    x_view[{i, j}] = tid;  
}  
  
...  
  
cuda::DMatrix<float> a({8, 8});  
  
kernel<<<1, 64>>>(cuda::dmatrix_view(a));
```

# Wrap-Up

- **Remote pointer types** are a **useful abstraction** for implementing distributed data structures
- Extendable to **multi-GPU data structures** both intra-node and multi-node
- Having the correct **high-level distributed data structures** can unlock performance competitive with highly tuned implementations

# Pointers

## Links

BCL, Our PGAS-Based C++ Distributed Data Structures Library

<https://github.com/berkeley-container-library/bcl>

My Website

<https://cs.berkeley.edu/~brock>



Interested in irregular data structures? Check out my other talk:

**GraphBLAS: Building a C++ Matrix API for Graph Algorithms (CppCon'21)**